

Frontal and multi-frontal solvers: Graph grammar based model of concurrency

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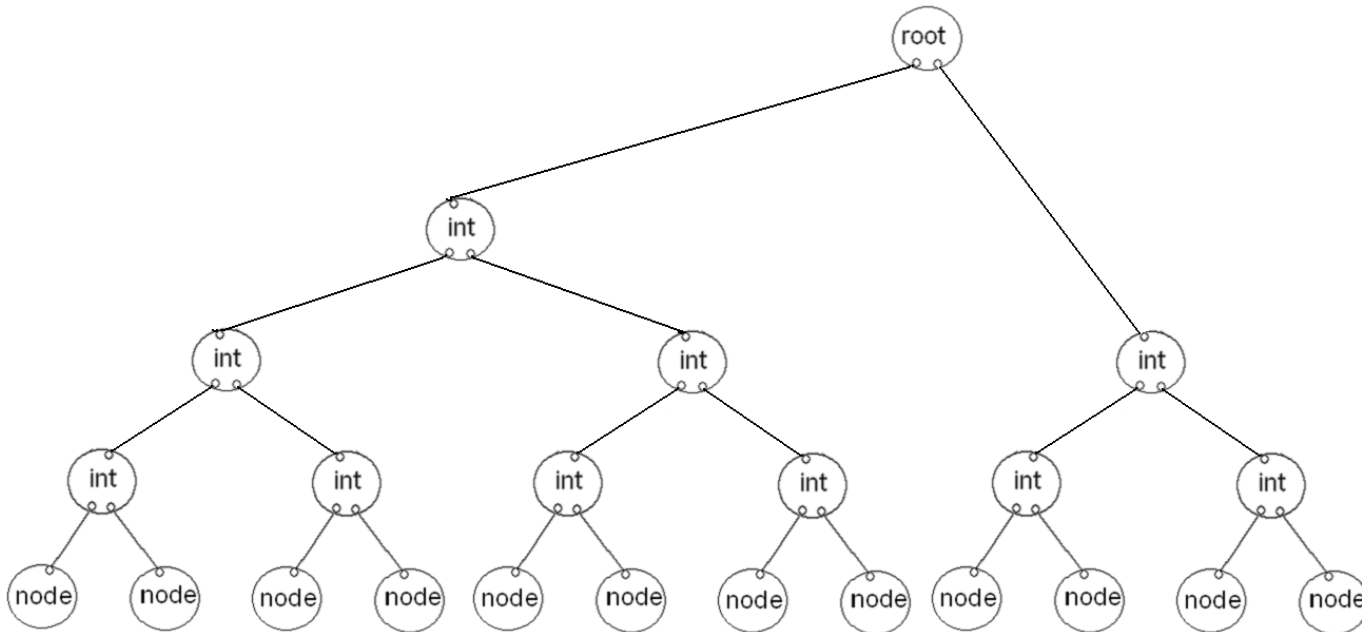
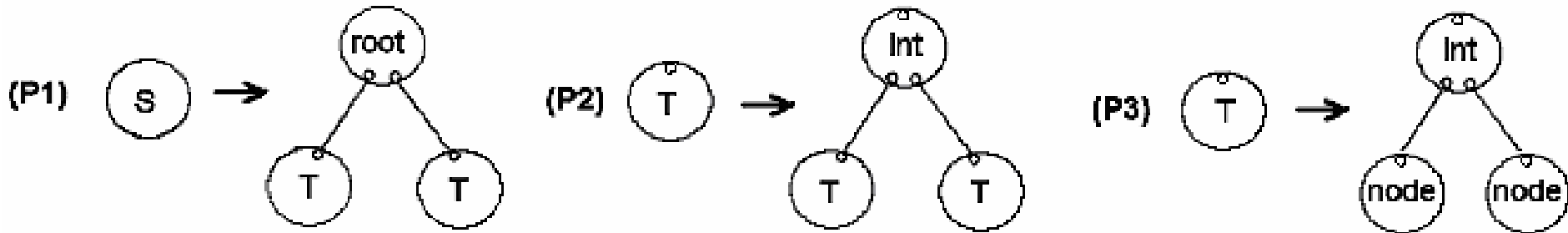
<http://www.ki.agh.edu.pl/en/research-groups/a2s>

Main collaborators

Victor Calo (KAUST)
Leszek Demkowicz (ICES, UT)
David Pardo (IKERBASQUE)

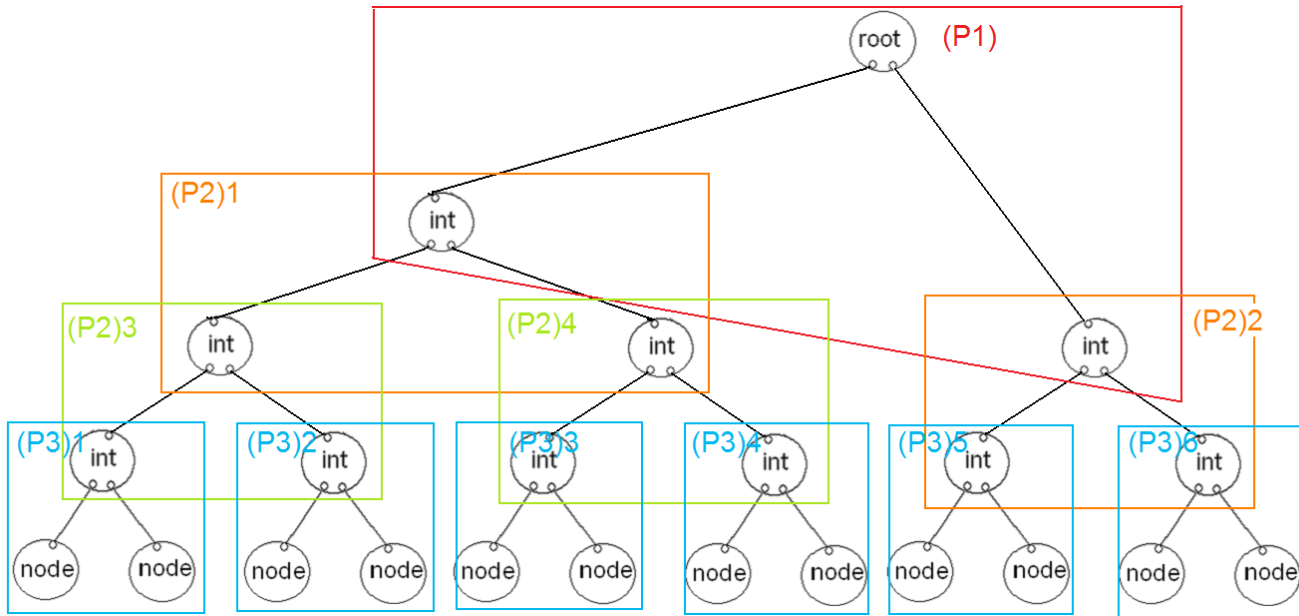
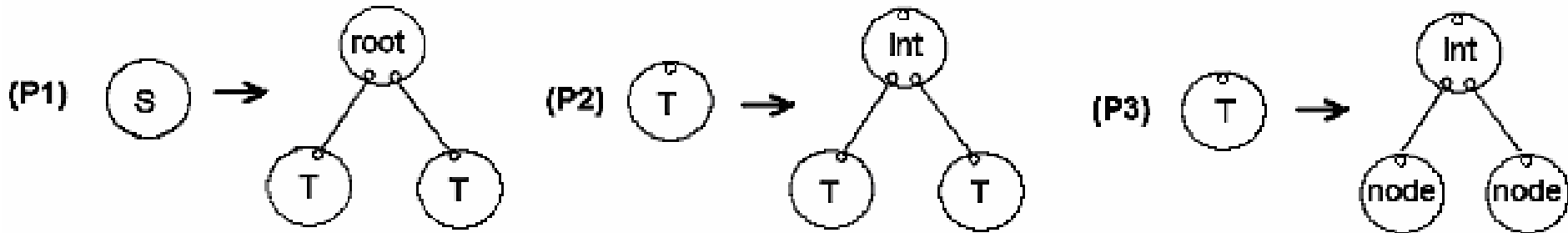


GENERATION OF 1D ELIMINATION TREE



1D elimination tree obtained by executing productions (P1)-(P2)²-(P2)²-(P3)⁶

GRAPH GRAMMAR PRODUCTIONS AS ATOMIC TASKS



We assign indices to grammar productions in order to localize the places where the graph grammar productions were fired

(P1)-(P2)₁-(P2)₂-(P2)₃-(P2)₄-(P3)₁-(P3)₂-(P3)₃-(P3)₄-(P3)₅-(P3)₆

TRACE THEORY BASED SCHEDULER

Alphabet:

$A = \{(P1), (P2)_1, (P2)_2, (P2)_3, (P2)_4, (P3)_1, (P3)_2, (P3)_3, (P3)_4, (P3)_5, (P3)_6\}$

Dependency relation for construction of the elimination tree

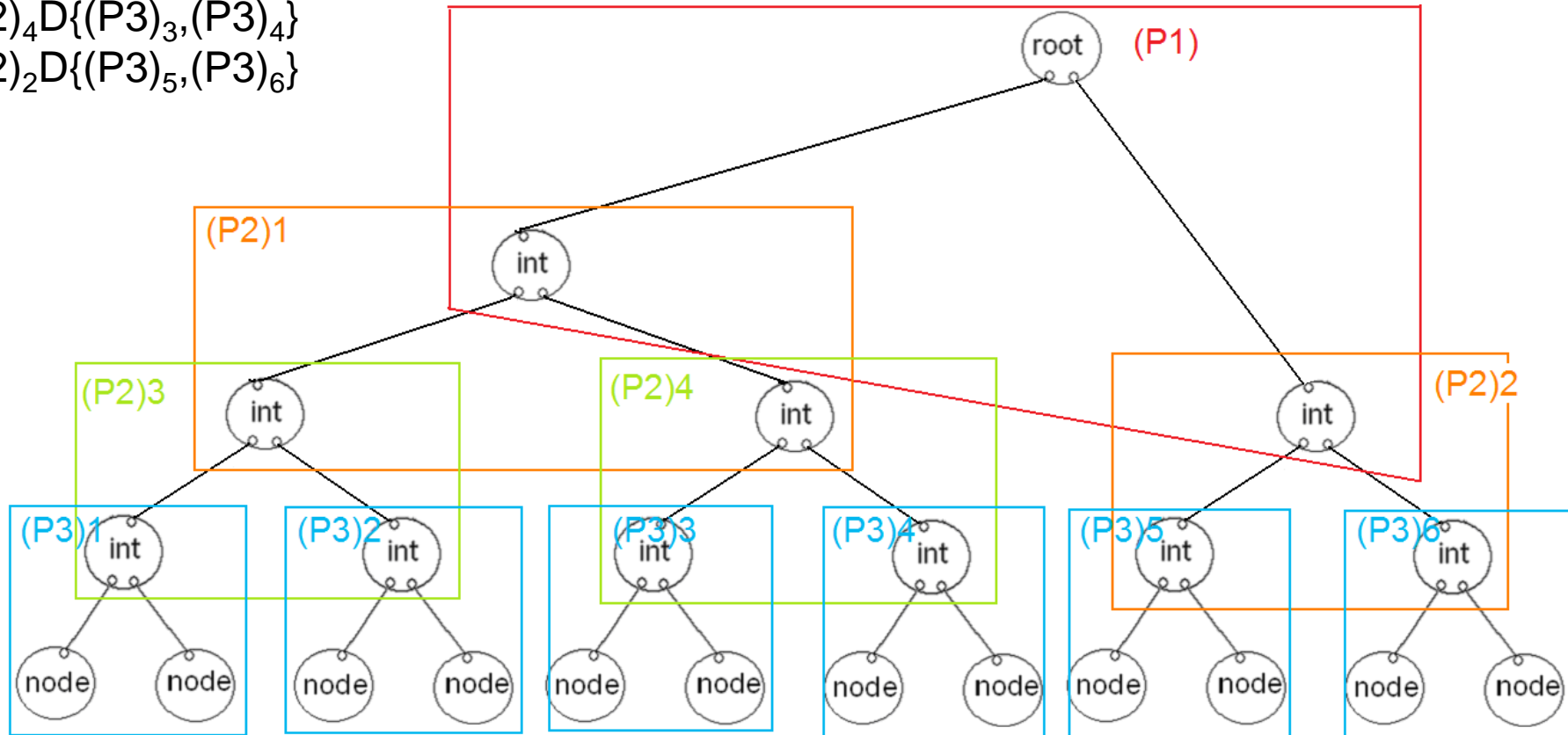
$(P1)D\{(P2)_1, (P2)_2\}$

$(P2)_1D\{(P2)_3, (P2)_4\}$

$(P2)_3D\{(P3)_1, (P3)_2\}$

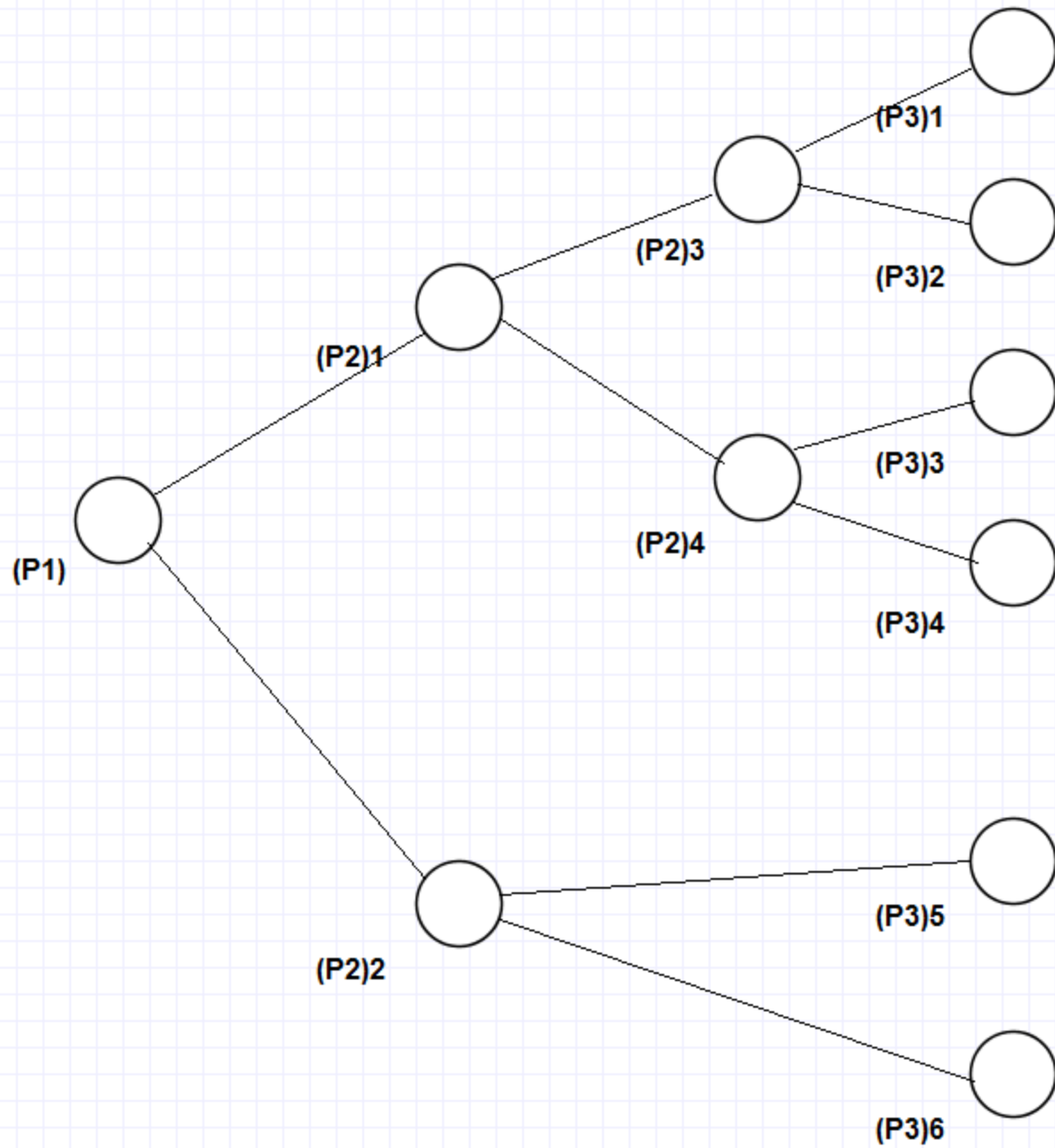
$(P2)_4D\{(P3)_3, (P3)_4\}$

$(P2)_2D\{(P3)_5, (P3)_6\}$



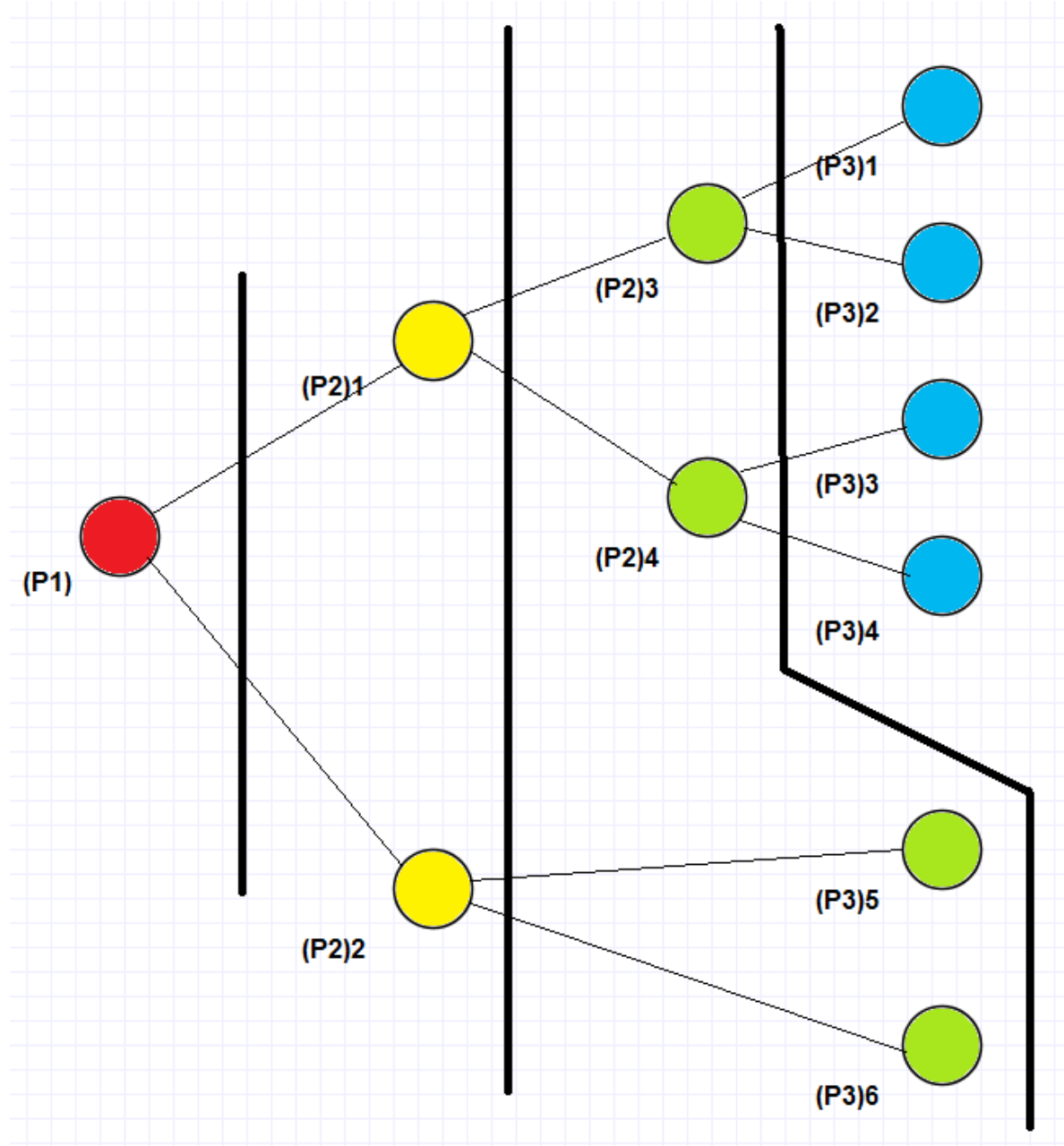
TRACE THEORY BASED SCHEDULER

Dependency graph



TRACE THEORY BASED SCHEDULER

Dependency graph



TRACE THEORY BASED SCHEDULER

(P1)-(P2)₁-(P2)₂-(P2)₃-(P2)₄-(P3)₁-(P3)₂-(P3)₃-(P3)₄-(P3)₅-(P3)₆

Foata Normal Form

$$\left[a_1^1 a_2^1 \dots a_{l_1}^1 \right] \left[a_1^2 a_2^2 \dots a_{l_2}^2 \right] \dots \left[a_1^n a_2^n \dots a_{l_n}^n \right]$$

$a_i^k \in A$ (alphabet)

$\forall k \forall i, j \in \{1, \dots, l_k\} \quad a_i^k I a_j^k \quad i <> j$ where $I = AxA \setminus D$

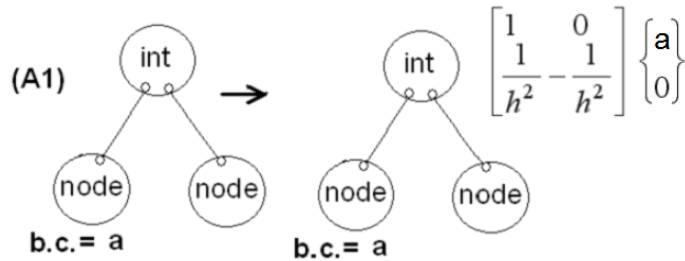
$\forall k \forall i \in \{1, \dots, l_k\} \exists j \in \{1, \dots, l_{k-1}\} \quad a_i^{k-1} D a_j^k$

Scheduling according to Foata Normal Form:

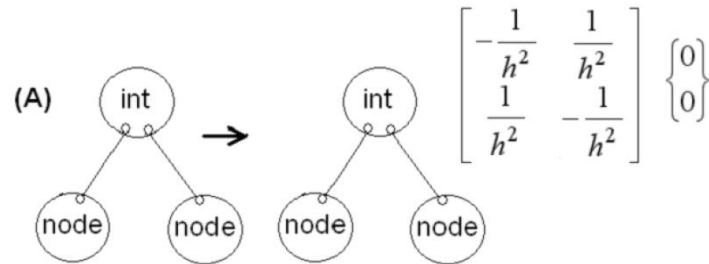
$[(P1)][(P2)_1(P2)_2][(P2)_3(P2)_4(P3)_5(P3)_6][(P3)_1(P3)_2(P3)_3(P3)_4]$

Thus, the execution of the solver consists of several steps, where independent tasks are executed in concurrent, interchanged with the synchronization barriers.

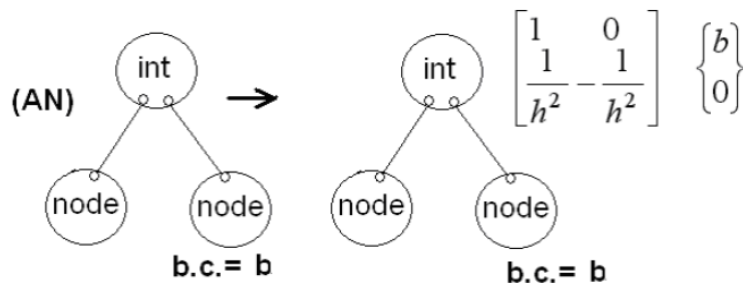
PROCESS OF THE ELIMINATION EXPRESSED BY GRAPH GRAMMAR PRODUCTIONS



Graph grammar production construction local matrix for the first sub-interval

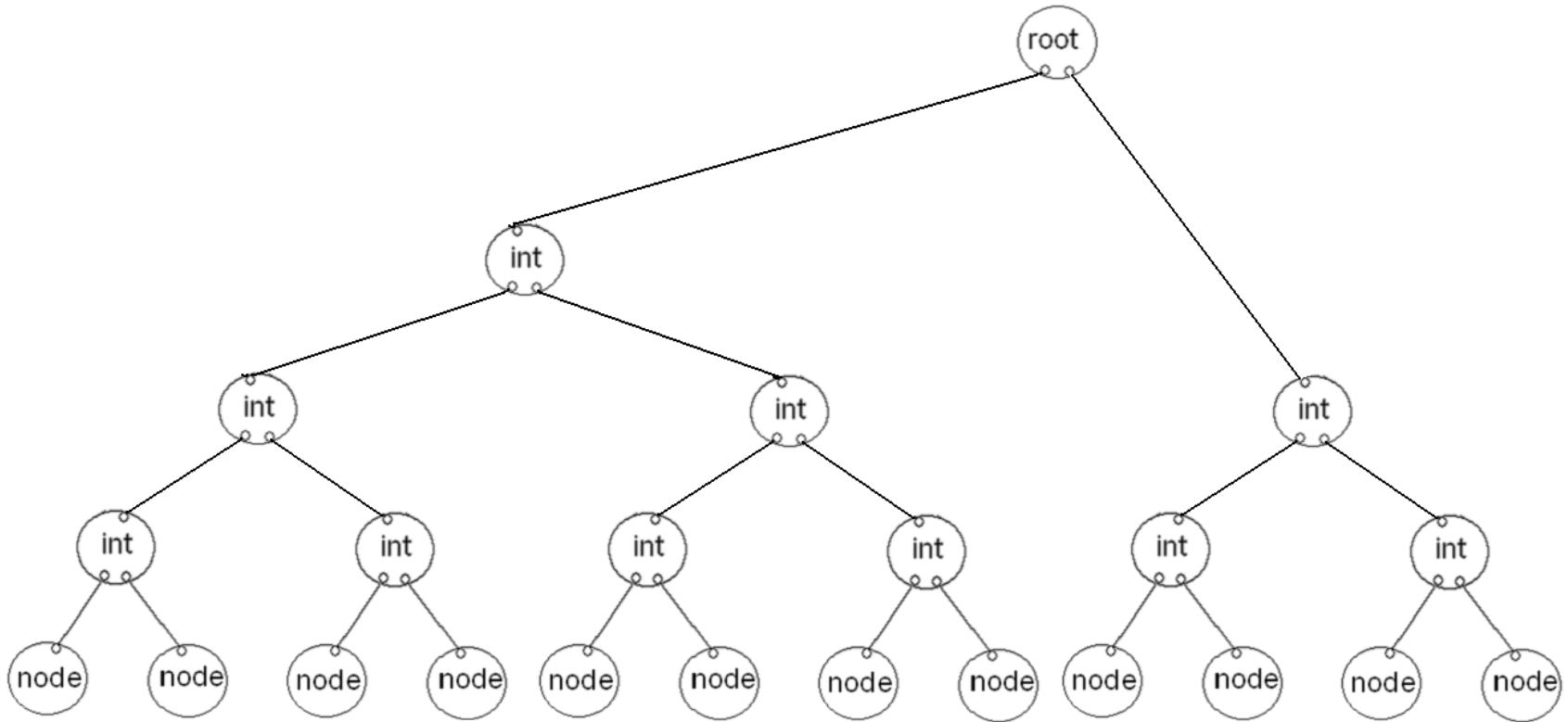


Graph grammar production construction local matrix for the i-th sub-interval



Graph grammar production construction local matrix for the last sub-interval

PROCESS OF THE ELIMINATION EXPRESSED BY GRAPH GRAMMAR PRODUCTIONS



$$\begin{array}{ccccccc}
 \boxed{\begin{matrix} 1 & 0 \\ 1/h^2 & -1/h^2 \end{matrix}} \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} &
 \boxed{\begin{matrix} -1/h^2 & 1/h^2 \\ 1/h^2 & -1/h^2 \end{matrix}} \begin{Bmatrix} x_2^{\text{II}} \\ x_3^{\text{I}} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} &
 \boxed{\begin{matrix} -1/h^2 & 1/h^2 \\ 1/h^2 & -1/h^2 \end{matrix}} \begin{Bmatrix} x_3^{\text{II}} \\ x_4^{\text{I}} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} &
 \boxed{\begin{matrix} -1/h^2 & 1/h^2 \\ 1/h^2 & -1/h^2 \end{matrix}} \begin{Bmatrix} x_4^{\text{II}} \\ x_5^{\text{I}} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} &
 \boxed{\begin{matrix} -1/h^2 & 1/h^2 \\ 1/h^2 & -1/h^2 \end{matrix}} \begin{Bmatrix} x_5^{\text{II}} \\ x_6^{\text{I}} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} &
 \boxed{\begin{matrix} -1/h^2 & 1/h^2 \\ 0 & 1 \end{matrix}} \begin{Bmatrix} x_6^{\text{II}} \\ x_7 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 20 \end{Bmatrix}
 \end{array}$$

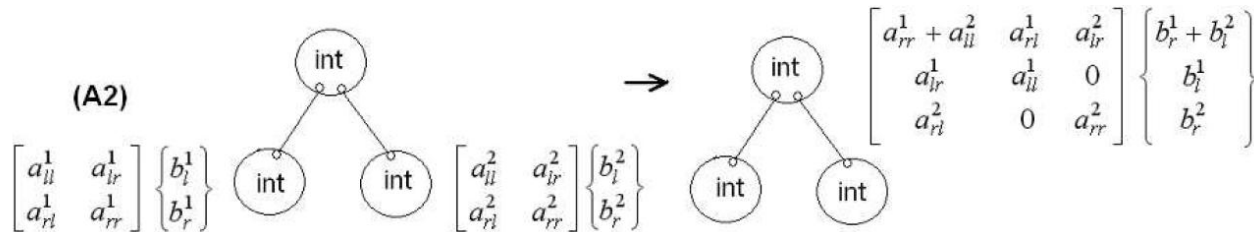
Generation of frontal matrices at leaves of the elimination tree expressed as the execution of graph grammar productions (A1)-(A)⁴-(AN)

PROCESS OF THE ELIMINATION EXPRESSED BY GRAPH GRAMMAR PRODUCTIONS

$$\begin{bmatrix} -\frac{1}{h^2} & \frac{1}{h^2} \\ \frac{1}{h^2} & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} x_{i-1} \\ x_i \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \oplus \begin{bmatrix} -\frac{1}{h^2} & \frac{1}{h^2} \\ \frac{1}{h^2} & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} x_i \\ x_{i+1} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} =$$

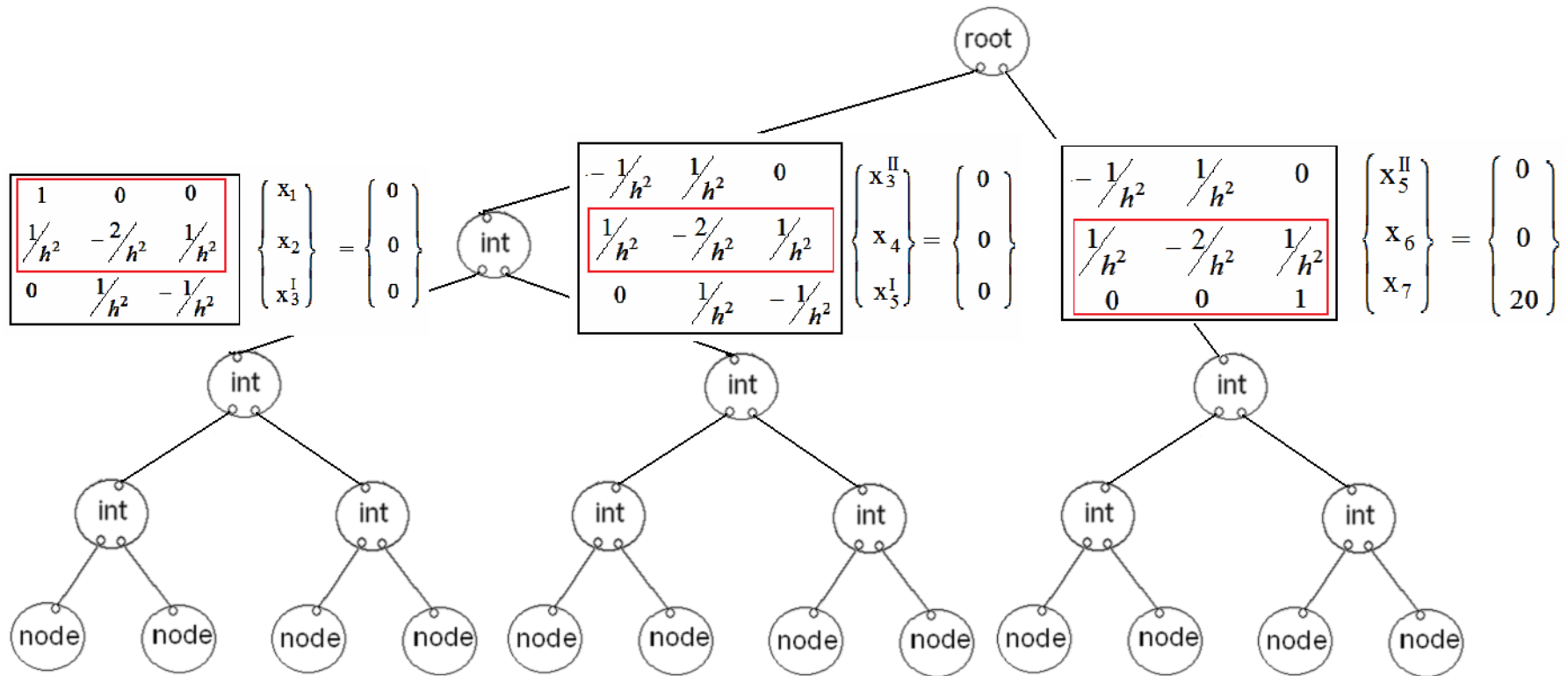
$$\begin{bmatrix} -\frac{2}{h^2} & \frac{1}{h^2} & \frac{1}{h^2} \\ \frac{1}{h^2} & -\frac{1}{h^2} & 0 \\ \frac{1}{h^2} & 0 & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} x_i \\ x_{i-1} \\ x_{i+1} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Exemplary merging of two internal contributions



Graph grammar production expressing the merging process

ASSEMBLING AT PARENT LEVEL



Expression of the solver execution by graph grammar productions

(A1)-(A)⁴-(AN) (generation of frontal matrices at leaves of the elimination trees)

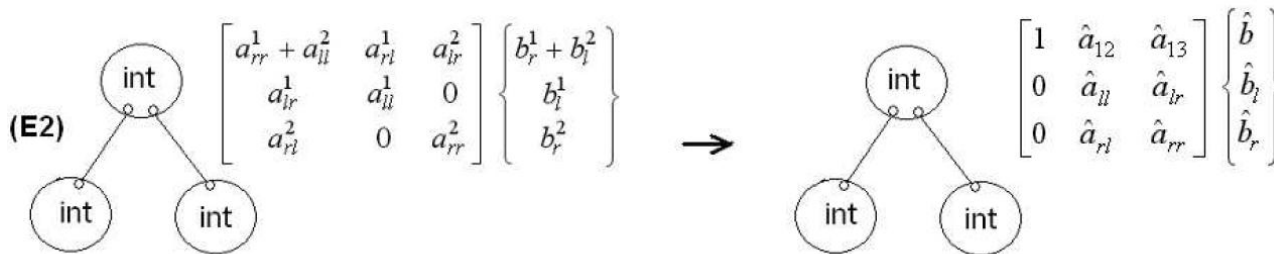
(A2)³ (merging contributions at father nodes)

PROCESS OF THE ELIMINATION EXPRESSED BY GRAPH GRAMMAR PRODUCTIONS

$$\begin{bmatrix} -\frac{1}{h^2} & \frac{1}{h^2} \\ \frac{1}{h^2} & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} x_{i-1} \\ x_i \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \oplus \begin{bmatrix} -\frac{1}{h^2} & \frac{1}{h^2} \\ \frac{1}{h^2} & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} x_i \\ x_{i+1} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} =$$

$$\begin{bmatrix} -\frac{2}{h^2} & \frac{1}{h^2} & \frac{1}{h^2} \\ \frac{1}{h^2} & -\frac{1}{h^2} & 0 \\ \frac{1}{h^2} & 0 & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} x_i \\ x_{i-1} \\ x_{i+1} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

After merging of the two internal contributions, $[x_{i-1}, x_i]$ and $[x_i, x_{i+1}]$ the i-th equation is fully assembled, and can be eliminated



Graph grammar production expressing the elimination process

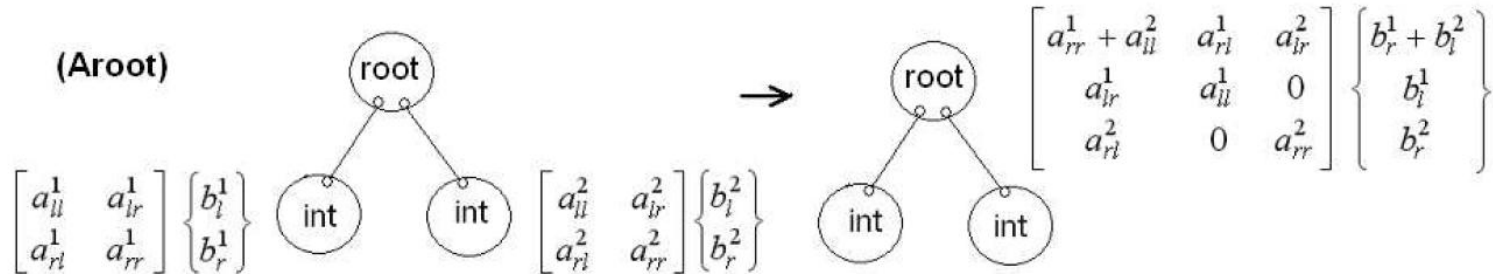
Expression of the solver execution by graph grammar productions

(A1)-(A)⁴-(AN) (generation of frontal matrices at leaves of the elimination trees)

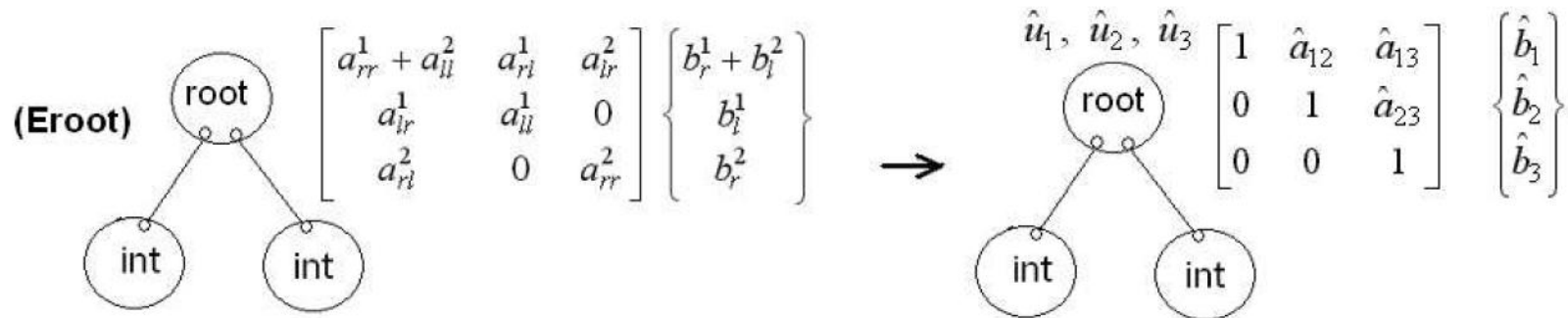
(A2)³ (merging contributions at father nodes)

(E2)³ (elimination of fully assembled nodes)

PROCESS OF THE ELIMINATION EXPRESSED BY GRAPH GRAMMAR PRODUCTIONS



Finally, we reach the root of the elimination tree



At the root node, all three equations are fully assembled, and the local system can be solved now

ELIMINATION OF FULLY ASSEMBLED NODES

Expression of the solver execution by graph grammar productions

(A1)-(A)⁴-(AN) (generation of frontal matrices at leaves of the elimination trees)

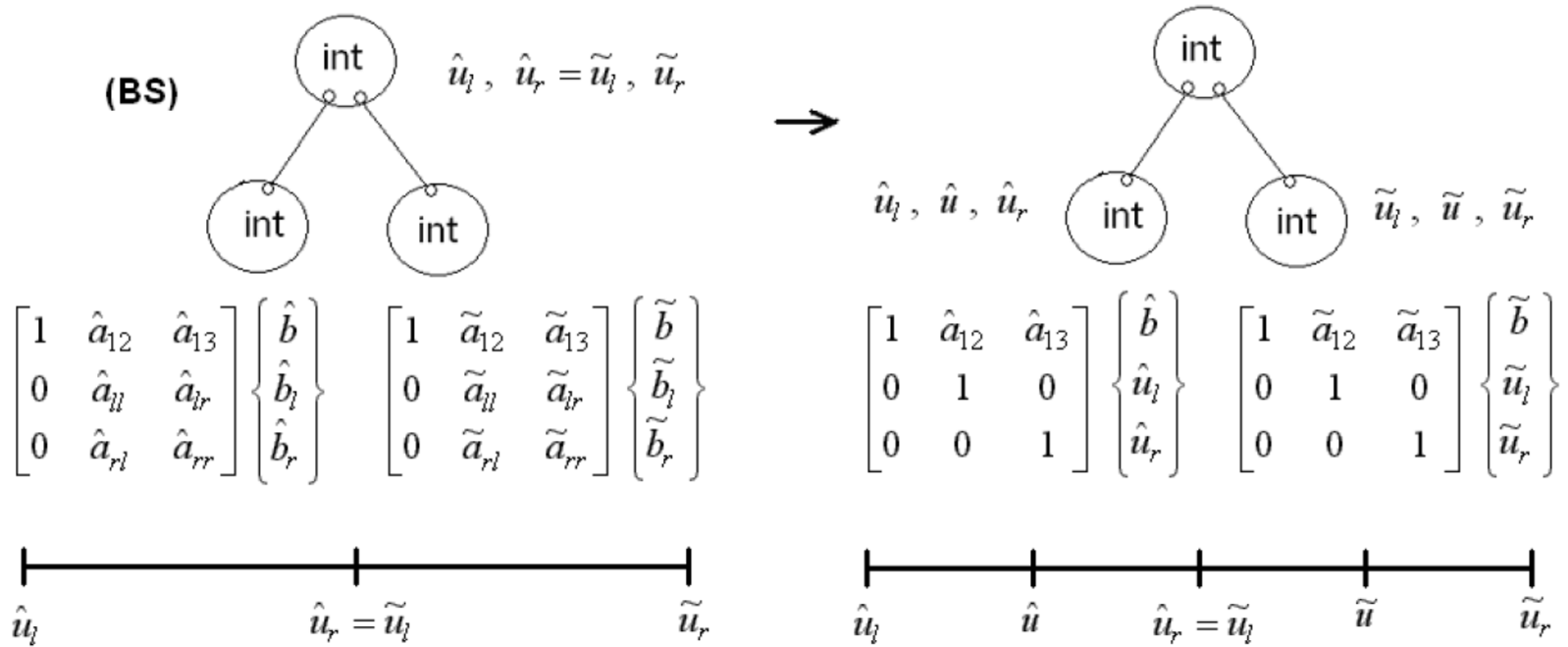
(A2)³ (merging contributions at father nodes)

(E2)³ (elimination of fully assembled nodes)

(A2) – (E2) (merging at parent node followed by elimination)

(Aroot) – (Eroot) (merging at root node followed by full forward elimination)

PROCESS OF THE BACKWARD SUBSTITUTIONS EXPRESSED BY GRAPH GRAMMAR PRODUCTIONS



At the last stage of the solver execution, we execute partial backward substitutions

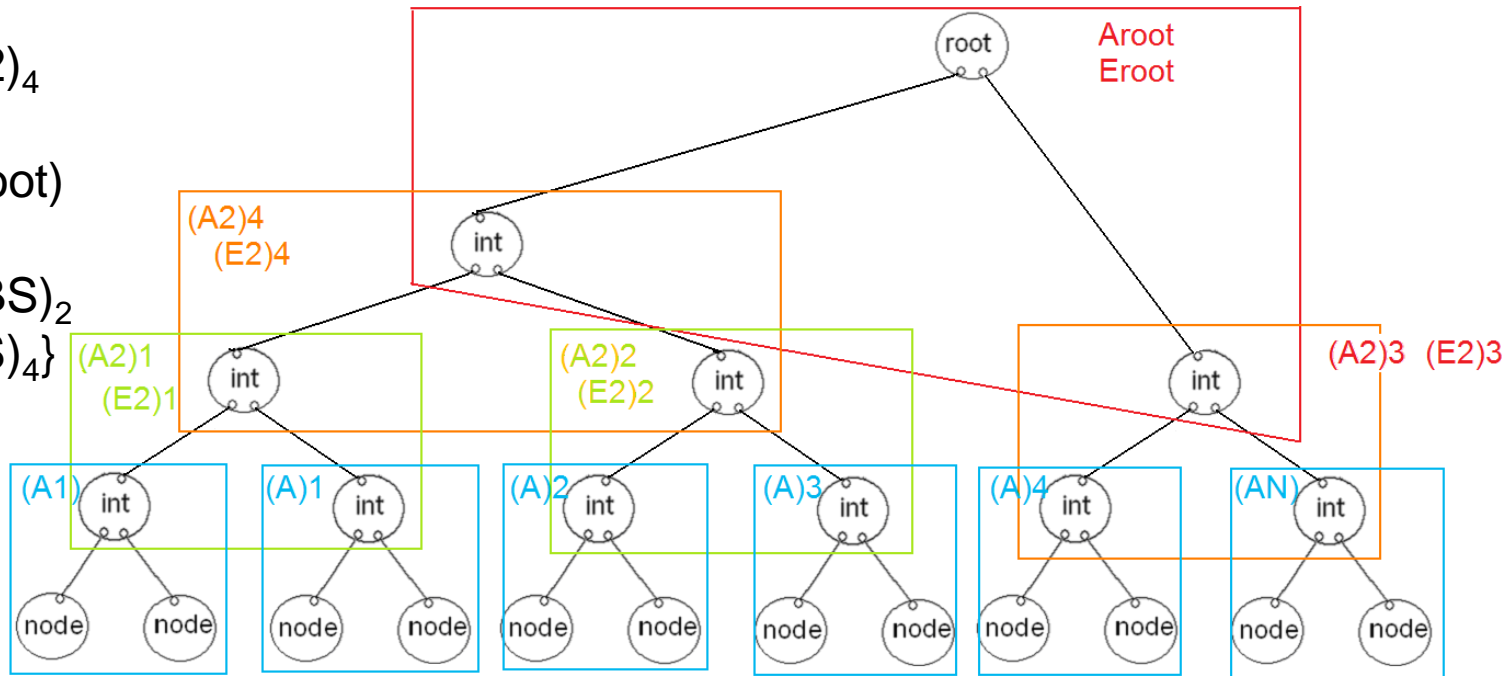
TRACE THEORY BASED SCHEDULER

Alphabet:

$A = \{(A1), (A)_1, (A)_2, (A)_3, (A)_4, (AN), (A2)_1, (A2)_2, (A2)_3, (E2)_1, (E2)_2, (E2)_3, (A2)_4, (E2)_4, (Aroot), (Eroot), (BS)_1, (BS)_2, (BS)_3, (BS)_4\}$

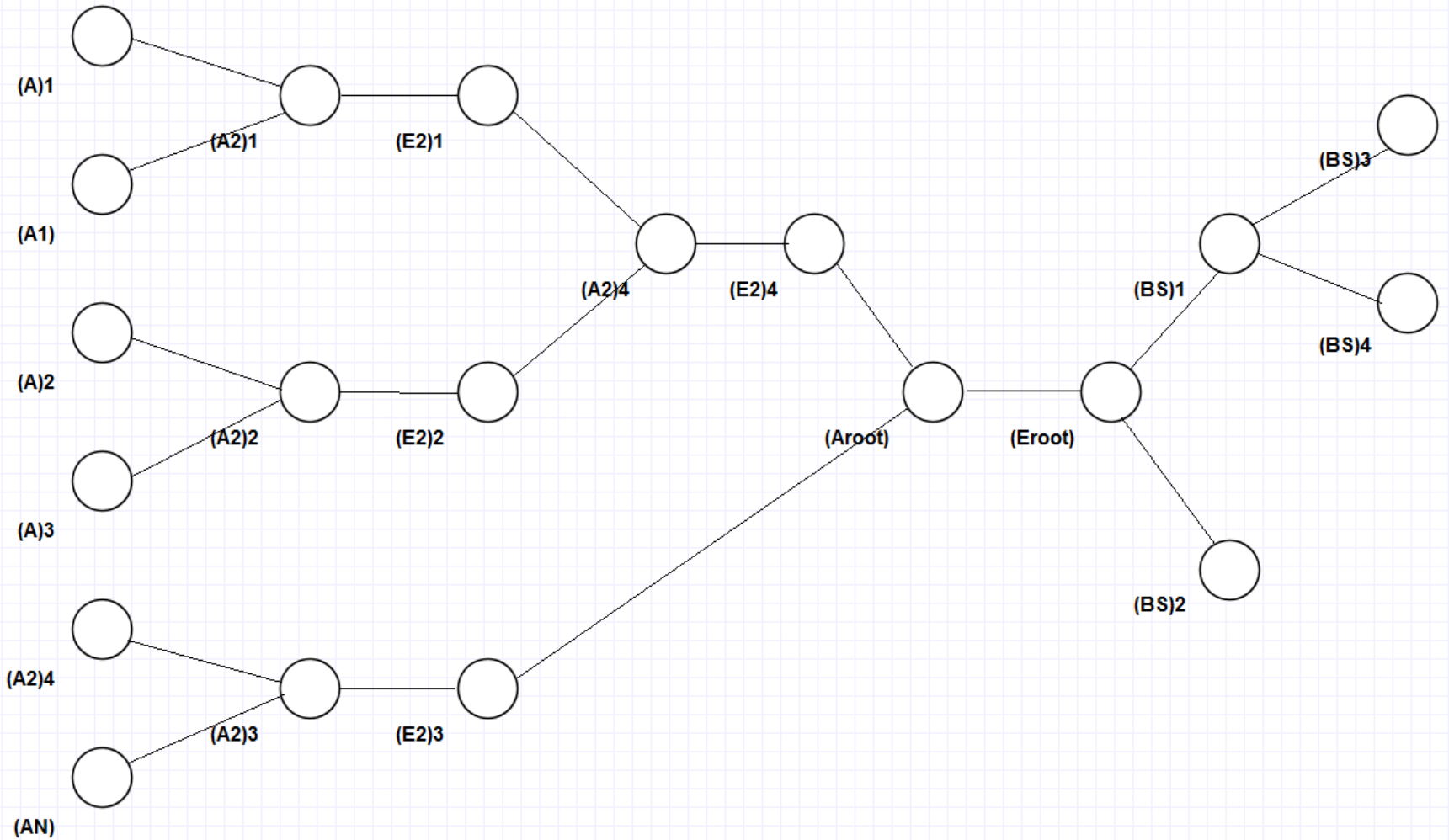
Dependency relation for the solver algorithm

$\{(A1), (A)_1\} D (A2)_1$
 $\{(A)_2, (A)_3\} D (A2)_2$
 $\{(A)_4, (AN)\} D (A2)_3$
 $(A2)_1 D (E2)_1$
 $(A2)_2 D (E2)_2$
 $(A2)_3 D (E2)_3$
 $\{(E2)_1, (E2)_2\} D (A2)_4$
 $(A2)_4 D (E2)_4$
 $\{(E2)_3, (E2)_4\} D (Aroot)$
 $(Aroot) D (Eroot)$
 $(Eroot) D \{(BS)_1, (BS)_2\}$
 $(BS)_1 D \{(BS)_3, (BS)_4\}$



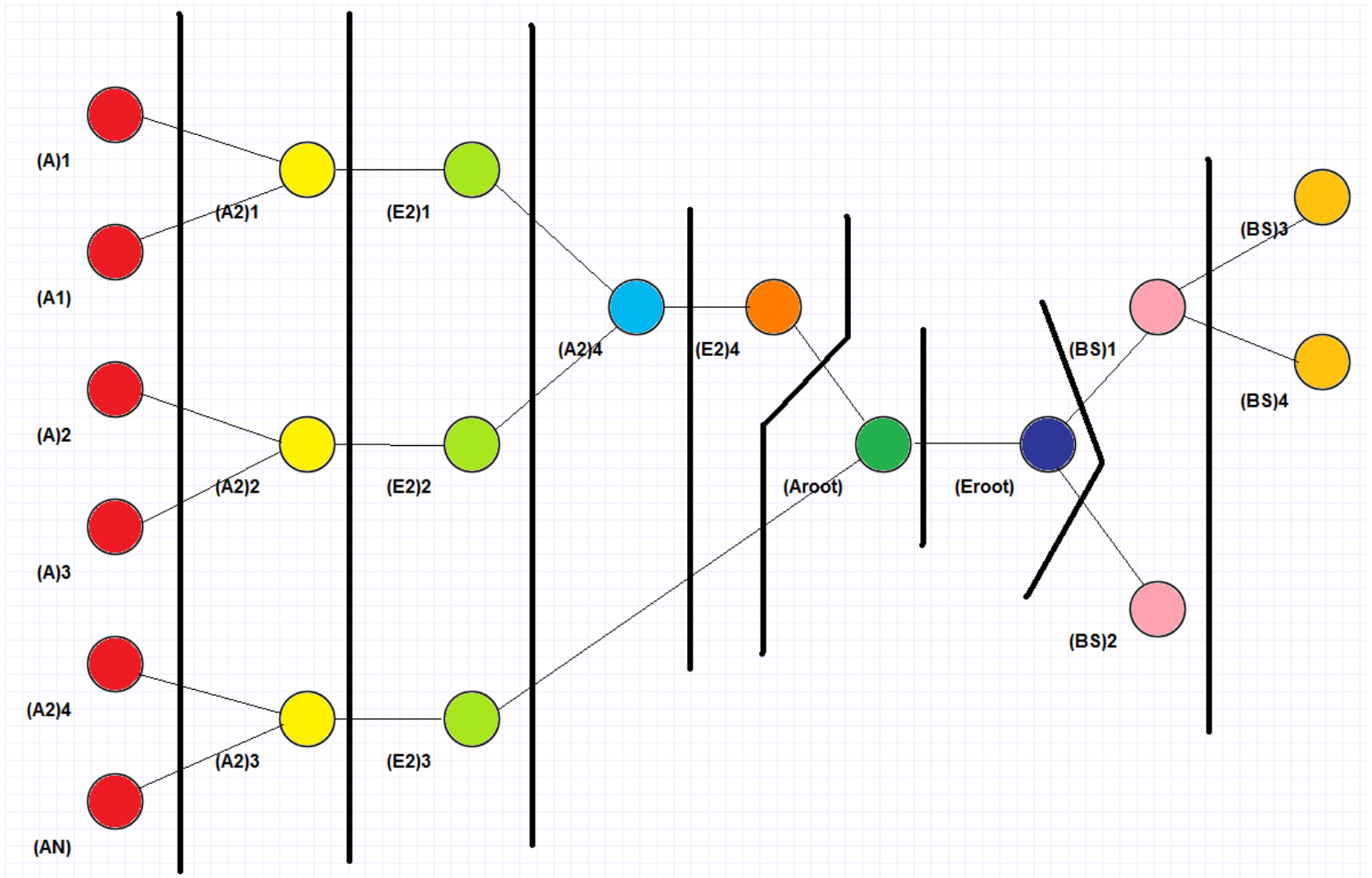
TRACE THEORY BASED SCHEDULER

Dependency graph



TRACE THEORY BASED SCHEDULER

Dependency graph



TRACE THEORY BASED SCHEDULER

(A1)-(A)₁-(A)₂-(A)₃-(A)₄- (AN)-(A2)₁-(A2)₂- (A2)₃-(E2)₁-(E2)₂-(E2)₃- (A2)₄- (E2)₄-
(Aroot)-(Eroot)-(BS)₁-(BS)₂-(BS)₃-(BS)₄

Foata Normal Form

$$\left[a_1^1 a_2^1 \dots a_{l_1}^1 \right] \left[a_1^2 a_2^2 \dots a_{l_2}^2 \right] \dots \left[a_1^n a_2^n \dots a_{l_n}^n \right]$$

$a_i^k \in A$ (alphabet)

$$\forall k \forall i, j \in \{1, \dots, l_k\} \quad a_i^k I a_j^k$$

$$\forall k \forall i \in \{1, \dots, l_k\} \exists j \in \{1, \dots, l_{k-1}\} \quad a_i^{k-1} D a_j^k$$

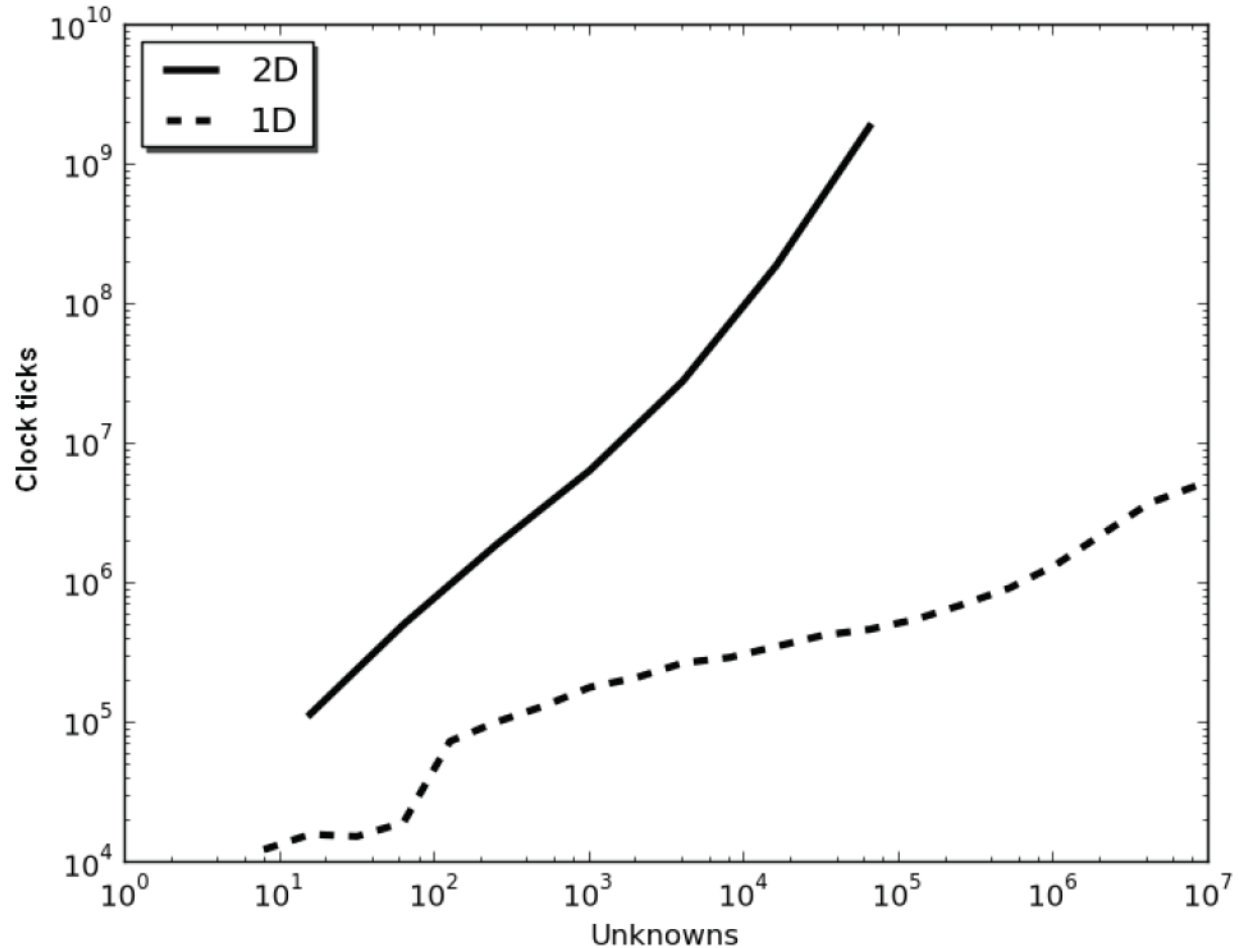
Scheduling according to Foata Normal Form:

[(A1)(A)₁(A)₂(A)₃(A)₄(AN)][(A2)₁(A2)₂(A2)₃][(E2)₁(E2)₂(E2)₃] [(A2)₄][(E2)₄]
[(Eroot)][(Aroot)][(Eroot)][(BS)₁(BS)₂][(BS)₃(BS)₄]

Thus, the execution of the solver consists of several steps, where independent tasks are executed in concurrent, interchanged with the synchronization barriers.

NUMERICAL EXPERIMENTS

NVIDIA GeForce 8800 gt with 16 multiprocessors, each having 8 cores
(128 cores total)



1D solver $O(\log N)$

2D solver $O(M \log N)$

When the number of leaves n is larger than number of processors,
the execution time must be multiplied by n/p

PAPERS

Paweł Obrok, Paweł Pierzchała, Arkadiusz Szymczak, Maciej Paszyński

**GRAPH GRAMMAR BASED MULTI-THREAD MULTI-FRONTAL PARALLEL
SOLVER WITH THRACE THEORY BASED SCHEDULER**

Procedia Computer Science, 1, 1 (2010) 1993-2001

