

MULTIVARIATE PÓLYA-SCHUR CLASSIFICATION PROBLEMS IN THE WEYL ALGEBRA

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ABSTRACT. A multivariate polynomial is *stable* if it is nonvanishing whenever all variables have positive imaginary parts. We classify all linear partial differential operators in the Weyl algebra \mathcal{A}_n that preserve stability. An important tool that we develop in the process is the higher dimensional generalization of Pólya-Schur's notion of multiplier sequence. We characterize all multivariate multiplier sequences as well as those of finite order. Next, we establish a multivariate extension of the Cauchy-Poincaré interlacing theorem and prove a natural analog of the Lax conjecture for real stable polynomials in two variables. Using the latter we describe all operators in \mathcal{A}_1 that preserve univariate hyperbolic polynomials by means of determinants and homogenized symbols. Our methods also yield homotopical properties for symbols of linear stability preservers and a duality theorem showing that an operator in \mathcal{A}_n preserves stability if and only if its Fischer-Fock adjoint does. These are powerful multivariate extensions of the classical Hermite-Poulain-Jensen theorem, Pólya's curve theorem and Schur-Maló-Szegő composition theorems. Examples and applications to strict stability preservers are also discussed.

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1. INTRODUCTION AND MAIN RESULTS

In their seminal 1914 paper [49] Pólya and Schur characterized all linear operators that are diagonal in the standard monomial basis of $\mathbb{C}[z]$ and preserve the set of polynomials with only real zeros. Polynomials of this type and linear transformations preserving them are of central interest in e.g. entire function theory [17, 37]: it is for instance well known that the Riemann Hypothesis is equivalent to saying that $\xi(\frac{1}{2} + it)$ may be approximated by real zero polynomials uniformly on compact sets, where ξ denotes Riemann's xi-function.

Pólya-Schur's result generated a vast literature on this subject and related topics, see [10] and references therein. Nevertheless, complete solutions to the fundamental problems of describing all linear operators preserving the set of real zero polynomials or, more generally, the set of polynomials with zero locus in a prescribed region $\Omega \subset \mathbb{C}$, are yet to be found. Although many special cases and variations of these problems have been intensely studied for more than a century, to the best of our knowledge they have been stated in the above general (and explicit) form only recently by Craven-Csordas [17] and Csordas [19], see also [1, 7, 10, 15].

This paper is part of a series [7, 8, 9, 11, 14, 15] devoted to these questions, their natural multivariate extensions and applications to geometric function theory, matrix theory, probability theory, combinatorics, and statistical mechanics. Here we

- (1) classify all linear partial differential operators in the n -th Weyl algebra that preserve stable, respectively real stable polynomials in n variables;
- (2) obtain a Lax type determinantal representation for linear operators in the first Weyl algebra ($n = 1$) preserving real zero polynomials and a characterization in terms of their homogenized symbols;
- (3) prove higher dimensional versions of Pólya-Schur's theorem;
- (4) apply (1)–(3) to establish a Fischer-Fock duality for stability preservers, homotopic properties of their symbols and geometric interpretations extending Pólya's "curve theorem" for all $n \geq 1$, stable multivariate generalizations of the Cauchy-Poincaré interlacing theorem, Schur-Maló-Szegő type convolution theorems in higher dimensions, and necessary and sufficient conditions for strict (real) stability preserving in one or several variables.

A nonzero univariate real polynomial with only real zeros is called *hyperbolic* while $f \in \mathbb{C}[z]$ is called *stable* if $f(z) \neq 0$ for all $z \in \mathbb{C}$ with $\Im(z) > 0$. Hence a univariate real polynomial is stable if and only if it is hyperbolic. These classical concepts have several natural extensions to multivariate polynomials, see, e.g., four different definitions in [33]. Below we concentrate on the most general notion:

Definition 1.1. A polynomial $f \in \mathbb{C}[z_1, \dots, z_n]$ is *stable* if $f(z_1, \dots, z_n) \neq 0$ for all n -tuples $(z_1, \dots, z_n) \in \mathbb{C}^n$ with $\Im(z_j) > 0$, $1 \leq j \leq n$. If in addition f has real coefficients it will be referred to as *real stable*.

Clearly, f is stable (respectively, real stable) if and only if for all $\alpha \in \mathbb{R}^n$ and $v \in \mathbb{R}_+^n$ the univariate polynomial $f(\alpha + vt) \in \mathbb{C}[t]$ is stable (respectively, hyperbolic), see Lemma 2.1 in Section 2. In what follows we denote by $\mathcal{H}_n(\mathbb{C})$, respectively $\mathcal{H}_n(\mathbb{R})$, the set of stable, respectively real stable polynomials in n variables.

Another fundamental extension of the notion of real-rootedness to higher dimensions stems from PDE theory. Namely, a homogeneous polynomial $p \in \mathbb{R}[z_1, \dots, z_n]$ is said to be (*Gårding*) *hyperbolic* with respect to a given vector $v \in \mathbb{R}^n$ if $p(v) \neq 0$

and for all vectors $\alpha \in \mathbb{R}^n$ the univariate polynomial $p(\alpha + vt) \in \mathbb{R}[t]$ has only real zeros. For background on (multivariate homogeneous) hyperbolic polynomials one may consult, e.g., [2, 26, 32]. In Section 6.2 we prove the following result describing the relation between real stable and hyperbolic polynomials.

Proposition 1.1. *Let $f \in \mathbb{R}[z_1, \dots, z_n]$ be of degree d and let $f_H \in \mathbb{R}[z_1, \dots, z_{n+1}]$ be the (unique) homogeneous polynomial of degree d such that $f_H(z_1, \dots, z_n, 1) = f(z_1, \dots, z_n)$. Then $f \in \mathcal{H}_n(\mathbb{R})$ if and only if f_H is hyperbolic with respect to every vector $v \in \mathbb{R}^{n+1}$ such that $v_{n+1} = 0$ and $v_i > 0$, $1 \leq i \leq n$.*

It is worth mentioning that real stable multivariate polynomials appear already in Theorem 1 of the foundational article [26] by Gårding and that stable multivariate entire functions can be found in Chap. IX of Levin's book [37].

Let $\mathcal{A}_n[\mathbb{C}]$ be the Weyl algebra of all finite order linear differential operators with polynomial coefficients on $\mathbb{C}[z_1, \dots, z_n]$. Recall the standard multi-index notation $z^\alpha = z_1^{\alpha_1} \dots z_n^{\alpha_n}$, $\partial^\alpha = \partial_1^{\alpha_1} \dots \partial_n^{\alpha_n}$, where $z = (z_1, \dots, z_n)$, $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$ and $\partial_i = \partial/\partial z_i$ for $1 \leq i \leq n$. Then each operator $T \in \mathcal{A}_n[\mathbb{C}]$ may be (uniquely) represented as

$$T = \sum_{\alpha, \beta \in \mathbb{N}^n} a_{\alpha\beta} z^\alpha \partial^\beta, \quad (1)$$

where $a_{\alpha\beta} \in \mathbb{C}$ is nonzero only for a finite number of pairs (α, β) . Let further $\mathcal{A}_n[\mathbb{R}]$ be the set of all $T \in \mathcal{A}_n[\mathbb{C}]$ with $a_{\alpha\beta} \in \mathbb{R}$ for all $\alpha, \beta \in \mathbb{N}^n$. A nonzero differential operator $T \in \mathcal{A}_n[\mathbb{C}]$ is called *stability preserving* if $T : \mathcal{H}_n(\mathbb{C}) \rightarrow \mathcal{H}_n(\mathbb{C}) \cup \{0\}$ and it is said to be *real stability preserving* if $T : \mathcal{H}_n(\mathbb{R}) \rightarrow \mathcal{H}_n(\mathbb{R}) \cup \{0\}$.

Given T of the form (1) define its *symbol* $F_T(z, w)$ to be the polynomial in $\mathbb{C}[z_1, \dots, z_n, w_1, \dots, w_n]$ given by $F_T(z, w) = \sum_{\alpha, \beta} a_{\alpha\beta} z^\alpha w^\beta$.

The first main results of this paper are the following characterizations of the multiplicative submonoids $\mathcal{A}_n(\mathbb{C}) \subset \mathcal{A}_n[\mathbb{C}]$ and $\mathcal{A}_n(\mathbb{R}) \subset \mathcal{A}_n[\mathbb{R}]$ consisting of all stability preservers and real stability preservers, respectively.

Theorem 1.2. *Let $T \in \mathcal{A}_n[\mathbb{C}]$. Then $T \in \mathcal{A}_n(\mathbb{C})$ if and only if $F_T(z, -w) \in \mathcal{H}_{2n}(\mathbb{C})$.*

Theorem 1.3. *Let $T \in \mathcal{A}_n[\mathbb{R}]$. Then $T \in \mathcal{A}_n(\mathbb{R})$ if and only if $F_T(z, -w) \in \mathcal{H}_{2n}(\mathbb{R})$.*

It is interesting to note that Theorems 1.2 and 1.3 essentially assert that *finite order stability (respectively, real stability) preservers in n variables are generated by stable (respectively, real stable) polynomials in $2n$ variables via the symbol map*. Geometric interpretations of these statements in terms of symbol surfaces are given in Section 4.4.

To prove the above theorems we need to generalize a large number of notions and results for univariate stable and hyperbolic polynomials to the multivariate case. Let $\alpha_1 \leq \alpha_2 \leq \dots \leq \alpha_n$ and $\beta_1 \leq \beta_2 \leq \dots \leq \beta_m$ be the zeros (counted with multiplicities) of two given polynomials $f, g \in \mathcal{H}_1(\mathbb{R})$ with $\deg f = n$ and $\deg g = m$. We say that these zeros *interlace* if they can be ordered so that either $\alpha_1 \leq \beta_1 \leq \alpha_2 \leq \beta_2 \leq \dots$ or $\beta_1 \leq \alpha_1 \leq \beta_2 \leq \alpha_2 \leq \dots$, in which case one clearly must have $|n - m| \leq 1$. Note that by our convention, the zeros of any two polynomials of degree 0 or 1 interlace. It is not difficult to show that if the zeros of f and g interlace then the *Wronskian* $W[f, g] := f'g - fg'$ is either nonnegative or nonpositive on the whole real axis \mathbb{R} , see, e.g., [51]. In the case when $W[f, g] \leq 0$

we say that f and g are in *proper position*, denoted $f \ll g$. For technical reasons we also say that the zeros of the polynomial 0 interlace the zeros of any (nonzero) hyperbolic polynomial and write $0 \ll f$ and $f \ll 0$. Note that if f, g are (nonzero) hyperbolic polynomials such that $f \ll g$ and $g \ll f$ then f and g must be constant multiples of each other, that is, $W[f, g] \equiv 0$.

The following theorem is a version of the classical Hermite-Biehler theorem [51].

Theorem 1.4 ((Hermite-Biehler theorem)). *Let $h := f + ig \in \mathbb{C}[z]$, where $f, g \in \mathbb{R}[z]$. Then $h \in \mathcal{H}_1(\mathbb{C})$ if and only if $g \ll f$.*

The Hermite-Biehler theorem gives an indication about how one should generalize the concept of interlacing to higher dimensions:

Definition 1.2. Two polynomials $f, g \in \mathbb{R}[z_1, \dots, z_n]$ are in *proper position*, denoted $f \ll g$, if $g + if \in \mathcal{H}_n(\mathbb{C})$.

Equivalently, f and g are in proper position if and only if for all $\alpha \in \mathbb{R}^n$ and $v \in \mathbb{R}_+^n$ the univariate polynomials $f(\alpha + vt), g(\alpha + vt) \in \mathbb{R}[t]$ are in proper position. It also follows that $f, g \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ whenever $f \ll g$, see Corollary 2.4 in Section 2.

The next (also classical) result is often attributed to Obreschkoff [45] and sometimes referred to as the Hermite-Kekeya-Obreschkoff theorem [51].

Theorem 1.5 ((Obreschkoff theorem)). *Let $f, g \in \mathbb{R}[z]$. Then $\alpha f + \beta g \in \mathcal{H}_1(\mathbb{R}) \cup \{0\}$ for all $\alpha, \beta \in \mathbb{R}$ if and only if either $f \ll g$, $g \ll f$ or $f = g \equiv 0$.*

We extend this theorem to polynomials in several variables as follows.

Theorem 1.6. *Let $f, g \in \mathbb{R}[z_1, \dots, z_n]$. Then $\alpha f + \beta g \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ for all $\alpha, \beta \in \mathbb{R}$ if and only if either $f \ll g$, $g \ll f$ or $f = g \equiv 0$.*

Recall that an infinite sequence of real numbers $\lambda : \mathbb{N} \rightarrow \mathbb{R}$ is called a *multiplier sequence (of the first kind)* if the associated linear operator T on $\mathbb{C}[z]$ defined by $T(z^n) = \lambda(n)z^n$, for all $n \in \mathbb{N}$, is a hyperbolicity preserver, i.e., $T : \mathcal{H}_1(\mathbb{R}) \rightarrow \mathcal{H}_1(\mathbb{R}) \cup \{0\}$. Any linear operator $T : \mathbb{C}[z_1, \dots, z_n] \rightarrow \mathbb{C}[z_1, \dots, z_n]$ can be represented as a formal power series in ∂ with polynomial coefficients. Indeed, this may be proved either by induction or by invoking Peetre's abstract characterization of differential operators [47]. Note also that in general a multiplier sequence is represented by an infinite order differential operator with polynomial coefficients.

In [49] Pólya and Schur gave the following characterization of multiplier sequences of the first kind.

Theorem 1.7 ((Pólya-Schur theorem)). *Let $\lambda : \mathbb{N} \rightarrow \mathbb{R}$ be a sequence of real numbers and $T : \mathbb{R}[z] \rightarrow \mathbb{R}[z]$ be the corresponding (diagonal) linear operator. Define $\Phi(z)$ to be the formal power series*

$$\Phi(z) = \sum_{k=0}^{\infty} \frac{\lambda(k)}{k!} z^k.$$

The following assertions are equivalent:

- (i) λ is a multiplier sequence,
- (ii) $\Phi(z)$ defines an entire function which is the limit, uniformly on compact sets, of polynomials with only real zeros of the same sign,

(iii) Either $\Phi(z)$ or $\Phi(-z)$ is an entire function that can be written as

$$Cz^n e^{az} \prod_{k=1}^{\infty} (1 + \alpha_k z),$$

where $n \in \mathbb{N}$, $C \in \mathbb{R}$, $a, \alpha_k \geq 0$ for all $k \in \mathbb{N}$ and $\sum_{k=1}^{\infty} \alpha_k < \infty$,

(iv) For all nonnegative integers n the polynomial $T[(1+z)^n]$ is hyperbolic with all zeros of the same sign.

We introduce a natural higher dimensional analog of the notion of multiplier sequence and completely characterize all multivariate multiplier sequences as well as those that can be represented as finite order differential operators. For this we need the following notation. Given an integer $n \geq 1$ and $\alpha, \beta \in \mathbb{N}^n$ we write $\alpha \leq \beta$ if $\alpha_i \leq \beta_i$ for $1 \leq i \leq n$. Let further $|\alpha| = |\alpha_1| + \dots + |\alpha_n|$, $\alpha^\beta = \alpha_1^{\beta_1} \dots \alpha_n^{\beta_n}$, $\alpha! = \alpha_1! \dots \alpha_n!$, $(\beta)_\alpha = 0$ if $\alpha \not\leq \beta$ and $(\beta)_\alpha = \beta! / (\beta - \alpha)!$ otherwise.

Definition 1.3. A function $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$ is a (multivariate) *multiplier sequence* if the corresponding (diagonal) linear operator T defined by $T(z^\alpha) = \lambda(\alpha)z^\alpha$, for all $\alpha \in \mathbb{N}^n$, is a real stability preserver, that is, $T : \mathcal{H}_n(\mathbb{R}) \rightarrow \mathcal{H}_n(\mathbb{R}) \cup \{0\}$.

The following theorem completely describes multivariate multiplier sequences.

Theorem 1.8. Consider an arbitrary map $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$. Then λ is a multivariate multiplier sequence if and only if there exist usual (univariate) multiplier sequences $\lambda_i : \mathbb{N} \rightarrow \mathbb{R}$, for all $1 \leq i \leq n$, such that

$$\lambda(\alpha) = \lambda_1(\alpha_1)\lambda_2(\alpha_2) \cdots \lambda_n(\alpha_n), \quad \text{for all } \alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n,$$

and either $\lambda(\alpha)\lambda(\beta) \geq 0$ for all $\alpha, \beta \in \mathbb{N}^n$, or $(-1)^{|\alpha|+|\beta|}\lambda(\alpha)\lambda(\beta) \geq 0$ for all $\alpha, \beta \in \mathbb{N}^n$.

Note that Theorem 1.8 is a negative result, since it shows that the only multivariate multiplier sequences are those that one would expect exist: products of univariate ones.

We next characterize all multiplier sequences that are finite order differential operators, i.e., those whose symbols are (finite degree) polynomials:

Theorem 1.9. Given a map $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$, let T be the corresponding (diagonal) linear operator. Then $T \in \mathcal{A}_n(\mathbb{R})$ if and only if T has a symbol $F_T(z, w)$ of the form

$$F_T(z, w) = f_1(z_1 w_1) f_2(z_2 w_2) \cdots f_n(z_n w_n),$$

where $f_i(t)$ is a polynomial with only real and nonpositive zeros for all $1 \leq i \leq n$.

Remark 1.1. Note that Theorem 1.9 combined with well-known properties of univariate multiplier sequences (cf. Lemma 3.1 below) implies in particular that if $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$ is a finite order multivariate multiplier sequence, then there exists $\gamma \in \mathbb{N}^n$ such that $\lambda(\alpha) = 0$ for $\alpha < \gamma$ and either $\lambda(\alpha) > 0$ for all $\alpha \geq \gamma$ or $\lambda(\alpha) < 0$ for all $\alpha \geq \gamma$. Note also that for $n = 1$ Theorem 1.9 gives an alternative description of finite order multiplier sequences that complements Pólya-Schur's Theorem 1.7.

Our next result is a vast generalization of the following classical theorem [51].

Theorem 1.10 ((Hermite-Poulain-Jensen theorem)). Let $p(z) = \sum_{k=0}^n a_k z^k \in \mathbb{R}[z]$ be nonzero and let $T = \sum_{k=0}^n a_k d^k / dz^k \in \mathcal{A}_1[\mathbb{R}]$. Then $T \in \mathcal{A}_1(\mathbb{R})$ if and only if $p \in \mathcal{H}_1(\mathbb{R})$.

The natural setting for our extension is the *Fischer-Fock space* \mathcal{F}_n [21, 22, 23, 24], also called the *Bargmann-Segal space* [3, 4, 55] or the *Newman-Shapiro space* [42, 43, 44, 56], which is the Hilbert space of holomorphic functions f on \mathbb{C}^n such that

$$\|f\|^2 = \sum_{\alpha \in \mathbb{N}^n} \alpha! |a(\alpha)|^2 = \pi^{-n} \int |f(z)|^2 e^{-|z|^2} dz_1 \wedge \cdots \wedge dz_n < \infty.$$

Here $\sum_{\alpha} a(\alpha)z^{\alpha}$ is the Taylor expansion of f . The inner product in \mathcal{F}_n is given by

$$\langle f, g \rangle = \pi^{-n} \int f(z) \overline{g(z)} e^{-|z|^2} dz_1 \wedge \cdots \wedge dz_n \quad (2)$$

and one can easily check that monomials $\{z^{\alpha}/\sqrt{\alpha!}\}_{\alpha \in \mathbb{N}^n}$ form an orthonormal basis. From this it follows that for $1 \leq i \leq n$ one has

$$\langle \partial_i z^{\alpha}, z^{\beta} \rangle = \alpha! \delta_{\alpha=\beta+e_i} = \langle z^{\alpha}, z_i z^{\beta} \rangle,$$

where δ is the Kronecker delta and e_i denotes the i -th standard generator of the lattice \mathbb{Z}^n . Hence, if $T = \sum_{\alpha, \beta} a_{\alpha\beta} z^{\alpha} \partial^{\beta} \in \mathcal{A}_n[\mathbb{C}]$ then

$$\langle T(f), g \rangle = \sum_{\alpha, \beta} a_{\alpha\beta} \langle z^{\alpha} \partial^{\beta} f, g \rangle = \sum_{\alpha, \beta} a_{\alpha\beta} \langle f, z^{\beta} \partial^{\alpha} g \rangle = \langle f, \sum_{\alpha, \beta} \overline{a_{\beta\alpha}} z^{\alpha} \partial^{\beta} g \rangle.$$

Therefore, the formal Fischer-Fock dual (or adjoint) operator of T is given by $T^* = \sum_{\alpha, \beta} \overline{a_{\beta\alpha}} z^{\alpha} \partial^{\beta}$, cf. [43]. Note that for $1 \leq i \leq n$ the dual of ∂_i is the operator given by multiplication with z_i and that diagonal operators (in the standard monomial basis) are self-dual. In particular, if T is a multiplier sequence then $T^* = T$.

Remark 1.2. The Fischer-Fock space \mathcal{F}_n was used by Dirac to define second quantization [20] and its inner product has since been rediscovered in various contexts, e.g. in number theory where the corresponding norm is known as the Bombieri norm [5, 53]. Further important properties of \mathcal{F}_n such as its (Bergman-Aronszajn) reproducing kernel and the Newman-Shapiro Isometry Theorem may be found in [42, 43, 44]. We should also point out that in e.g. \mathcal{D} -module theory and microlocal Fourier analysis [40] one usually works with the inner product on \mathcal{F}_n defined by $\langle f(z), g(z) \rangle_d = \langle f(iz), g(iz) \rangle$, where $\langle \cdot, \cdot \rangle$ is as in (2). Note that the dual operator of ∂_i with respect to $\langle \cdot, \cdot \rangle_d$ is the operator given by multiplication with $-z_i$.

In Section 4.4 we give a geometric interpretation and proof of the fact that the duality map with respect to the above scalar product preserves both $\mathcal{A}_n(\mathbb{C})$ and $\mathcal{A}_n(\mathbb{R})$. More precisely, from Theorems 1.2–1.3 we deduce the following natural property:

Theorem 1.11 ((Duality theorem)). *Let $T \in \mathcal{A}_n[\mathbb{C}]$. Then $T \in \mathcal{A}_n(\mathbb{C})$ if and only if $T^* \in \mathcal{A}_n(\mathbb{C})$. Similarly, if $T \in \mathcal{A}_n[\mathbb{R}]$ then $T \in \mathcal{A}_n(\mathbb{R})$ if and only if $T^* \in \mathcal{A}_n(\mathbb{R})$.*

We conclude this introduction with a series of examples of real stable polynomials and various applications of our results. Further interesting examples of multi-affine stable and real stable polynomials can be found in e.g. [9, 11, 14, 16].

Proposition 1.12. *Let A_1, \dots, A_n be positive semidefinite $m \times m$ matrices and let B be a complex Hermitian $m \times m$ matrix. Then the polynomial*

$$f(z_1, \dots, z_n) = \det \left(\sum_{i=1}^n z_i A_i + B \right) \quad (3)$$

is either real stable or identically zero.

A proof of the above proposition is given in Section 6. Using this result and Theorem 1.2 we obtain a multidimensional generalization of the Cauchy-Poincaré interlacing theorem: see Theorem 6.2 in Section 6.1.

The Lax conjecture [35] for (Gårding) hyperbolic polynomials in three variables has recently been settled by Lewis, Parillo and Ramana [38]. Their proof relies on the results of Helton and Vinnikov [30]. Applications of these results to e.g. hyperbolic programming and convex optimization may be found in [52]. In Section 6.2 we prove the following converse to Proposition 1.12 in the case $n = 2$ and thus establish a natural analog of the Lax conjecture for real stable polynomials in two variables.

Theorem 1.13. *Any real stable polynomial in two variables x, y can be written as $\pm \det(xA + yB + C)$ where A and B are positive semidefinite matrices and C is a symmetric matrix of the same order.*

Remark 1.3. A characterization of real stable polynomials in an arbitrary number of variables has recently been obtained in [14].

Combining Theorem 1.13 with Theorem 1.3 we get two new descriptions of finite order linear preservers of hyperbolicity (i.e., univariate real stability), namely a determinantal characterization and one in terms of homogenized operator symbols: see Theorems 6.8 and 6.9 in Section 6.3.

Further applications of our results include multivariate Schur-Maló-Szegő composition formulas and closure properties under the Weyl product of (real) stable polynomials (Section 4.3), a unified treatment of Pólya type “curve theorems” as well as multivariate extensions (Section 4.4), and necessary and sufficient criteria for strict stability and strict real stability preservers (Section 5).

Brief excursion around the literature. The study of univariate stable polynomials was initiated by Hermite in the 1860’s and continued by Laguerre, Maxwell, Routh, Hurwitz and many others in the second half of the XIX-th century. The contributions of the classical period are well summarized in [25, 50, 51]. Important results on stability of entire functions were obtained in the mid XX-th century by e.g. Krein, Pontryagin, Chebotarev, Levin [37]. Modern achievements in this area can be found in [46] and references therein. Much less seems to be known concerning multidimensional stability. In control theory one can name a series of papers by Kharitonov *et al.* [33] with numerous references to the earlier literature on this topic. Another origin of interest to multivariate stable polynomials comes from an unexpected direction, namely the Lee-Yang theorem on ferromagnetic Ising models, the Heilmann-Lieb theorem for monomer-dimer systems and their various generalizations [29, 36, 39]. Combinatorial theory provides yet another rich source of stable polynomials as multivariate spanning tree polynomials and generating polynomials for various classes of matroids turn out to be stable (cf., e.g., [14, 16]). Multivariate stable polynomials were recently used in [28] to generalize and reprove in a unified manner a number of classical conjectures, including the van der Waerden and Schrijver-Valiant conjectures, and in [9] to solve some long-standing conjectures of Johnson and Bapat in matrix theory. Further recent contributions include [8], where a complete classification of linear preservers of univariate polynomials with only real zeros – and, more generally, of univariate polynomials with zeros only in a closed circular domain or on the boundary of such a domain – has been obtained, thus solving an old open problem going back to

Laguerre [34] and Pólya-Schur [49]. Let us finally mention that real stable polynomials have also found remarkable applications in probability theory and interacting particle systems. Indeed, these polynomials were recently used in [11] to develop a theory of negative dependence for the class of strongly Rayleigh probability measures, which contains several important examples such as uniform random spanning tree measures, fermionic/determinantal measures, balls-and-bins measures and distributions for symmetric exclusion processes.

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2. BASIC PROPERTIES AND GENERALIZED HERMITE-KAKEYA-OBRESCHKOFF THEOREM

The following criterion for (real) stability is an easy consequence of the definitions.

Lemma 2.1. *Let $f \in \mathbb{C}[z_1, \dots, z_n]$. Then $f \in \mathcal{H}_n(\mathbb{C})$ if and only if $f(\alpha + vt) \in \mathcal{H}_1(\mathbb{C})$ for all $\alpha \in \mathbb{R}^n$ and $v \in \mathbb{R}_+^n$.*

The next lemma extends the Hermite-Biehler theorem to the multivariate case and provides a useful alternative description of the proper position/“interlacing” property for multivariate polynomials.

Lemma 2.2. *Let $f, g \in \mathbb{R}[z_1, \dots, z_n]$ and let z_{n+1} be a new indeterminate. Then $f \ll g$ if and only if $g + z_{n+1}f \in \mathcal{H}_{n+1}(\mathbb{R})$. Moreover, if $f \in \mathcal{H}_n(\mathbb{R})$ then $f \ll g$ if and only if*

$$\Im \left(\frac{g(z)}{f(z)} \right) \geq 0$$

whenever $\Im(z_i) > 0$ for all $1 \leq i \leq n$.

Proof. The “if” direction is obvious. Suppose that $f \ll g$ and that $z_{n+1} = a + ib$, where $a \in \mathbb{R}$ and $b \in \mathbb{R}_+$. Then by Lemma 2.1 we have that $f(\alpha + vt) \ll g(\alpha + vt)$ for all $\alpha \in \mathbb{R}^n$ and $v \in \mathbb{R}_+^n$. By Obreschkoff’s theorem the zeros of $g(\alpha + vt) + af(\alpha + vt)$ and $bf(\alpha + vt)$ interlace (both cannot be identically zero). Moreover,

$$W(bf(\alpha + vt), g(\alpha + vt) + af(\alpha + vt)) = bW(f(\alpha + vt), g(\alpha + vt)).$$

Thus $bf(\alpha + vt) \ll g(\alpha + vt) + af(\alpha + vt)$ for all $\alpha \in \mathbb{R}^n$ and $v \in \mathbb{R}_+^n$, which by Lemma 2.1 implies that $g + (a + ib)f \in \mathcal{H}_n(\mathbb{C})$. But $g + z_{n+1}f$ clearly has real coefficients so $g + z_{n+1}f \in \mathcal{H}_{n+1}(\mathbb{R})$. The final statement of the lemma is a simple consequence of the above arguments. \square

Lemma 2.3. *Suppose that $f_j \in \mathbb{C}[z_1, \dots, z_n]$ for all $j \in \mathbb{N}$ are nonvanishing in an open set $U \subseteq \mathbb{C}^n$ and that f is the limit, uniformly on compact sets, of the sequence $\{f_j\}_{j \in \mathbb{N}}$. Then f is either nonvanishing in U or it is identically equal to 0.*

Proof. The lemma follows from the multivariate version of Hurwitz’ theorem on the continuity of zeros of analytic functions, see, e.g., [16]. \square

Let $f(z_1, \dots, z_n) \in \mathcal{H}_n(\mathbb{C})$, $\alpha \in \mathbb{R}$ and $\lambda > 0$. Then $f(\alpha + \lambda z_1, \dots, z_n) \in \mathcal{H}_n(\mathbb{C})$. By letting $\lambda \rightarrow 0$ we have by Lemma 2.3 that $f(\alpha, z_2, \dots, z_n) \in \mathcal{H}_{n-1}(\mathbb{C}) \cup \{0\}$.

Corollary 2.4. *For each $n \in \mathbb{N}$ one has*

$$\mathcal{H}_n(\mathbb{C}) = \{g + if : f, g \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}, f \ll g\}.$$

Proof. The only novel part is that $f, g \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ whenever $f \ll g$. This follows from Lemma 2.2 and Lemma 2.3 when we let z_{n+1} tend to 0 and ∞ , respectively. \square

We are ready to prove our multivariate Obreschkoff theorem.

of Theorem 1.6. Suppose that $f \ll g$. By Corollary 2.4 we have $g \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ so we can normalize and set $\beta = 1$. By Lemma 2.2 we have $g + z_{n+1}f \in \mathcal{H}_{n+1}(\mathbb{R}) \subset \mathcal{H}_{n+1}(\mathbb{C})$, so by letting $z_{n+1} = i + \alpha$ with $\alpha \in \mathbb{R}$ we have $g + \alpha f + if \in \mathcal{H}_n(\mathbb{C})$, i.e., $f \ll g + \alpha f$. From Corollary 2.4 again it follows that $g + \alpha f \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$, as was to be shown.

To prove the converse statement suppose that we do not have $f = g \equiv 0$. If $\alpha f + \beta g \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ for all $\alpha, \beta \in \mathbb{R}$ then (by Lemma 2.1 and Obreschkoff's theorem) for all $\gamma \in \mathbb{R}^n$ and $v \in \mathbb{R}_+^n$ we have either $f(\gamma + vt) \ll g(\gamma + vt)$ or $f(\gamma + vt) \gg g(\gamma + vt)$. If both instances occur for different vectors, i.e., $f(\gamma_1 + v_1 t) \ll g(\gamma_1 + v_1 t)$ and $f(\gamma_2 + v_2 t) \gg g(\gamma_2 + v_2 t)$ for some $\gamma_1, \gamma_2 \in \mathbb{R}^n$ and $v_1, v_2 \in \mathbb{R}_+^n$, then by continuity arguments there exists $\tau \in [0, 1]$ such that $f(\gamma_\tau + v_\tau t) \ll g(\gamma_\tau + v_\tau t)$ and $f(\gamma_\tau + v_\tau t) \gg g(\gamma_\tau + v_\tau t)$, where $\gamma_\tau := \tau\gamma_1 + (1 - \tau)\gamma_2 \in \mathbb{R}^n$ and $v_\tau := \tau v_1 + (1 - \tau)v_2 \in \mathbb{R}_+^n$. This means that $f(\gamma_\tau + v_\tau t)$ and $g(\gamma_\tau + v_\tau t)$ are constant multiples of each other, say $f(\gamma_\tau + v_\tau t) = \lambda g(\gamma_\tau + v_\tau t)$ for some $\lambda \in \mathbb{R}$. By hypothesis we have $h := f - \lambda g \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ and $h(\gamma_\tau + v_\tau t) \equiv 0$, in particular $h(\gamma_\tau + iv_\tau) = 0$. Since $v_\tau \in \mathbb{R}_+^n$ it follows that $h \equiv 0$ and $f = \lambda g$. Consequently, if both instances occur we have $f \ll g$ for trivial reasons. Thus we may assume that only one of them occurs. But then the conclusion follows from Lemma 2.1. \square

Define

$$\mathcal{H}_n(\mathbb{C})^- = \{f \in \mathbb{C}[z_1, \dots, z_n] : f(z_1, \dots, z_n) \neq 0 \text{ if } \Im(z_i) < 0 \text{ for } 1 \leq i \leq n\}.$$

Clearly, $f(z) \in \mathcal{H}_n(\mathbb{C})$ if and only if $f(-z) \in \mathcal{H}_n(\mathbb{C})^-$. Hence by Corollary 2.4 and Lemma 2.1 we have $h := g + if \in \mathcal{H}_n(\mathbb{C})^-$ with $f, g \in \mathbb{R}[z_1, \dots, z_n]$ if and only if $g \ll f$.

Proposition 2.5. *For any $n \in \mathbb{N}$ the following holds:*

$$\mathcal{H}_n(\mathbb{C}) \cap \mathcal{H}_n(\mathbb{C})^- = \mathbb{C}\mathcal{H}_n(\mathbb{R}) := \{cf : c \in \mathbb{C}, f \in \mathcal{H}_n(\mathbb{R})\}.$$

Proof. Suppose that $h = g + if \in \mathcal{H}_n(\mathbb{C}) \cap \mathcal{H}_n(\mathbb{C})^-$. By Corollary 2.4 we have $f \ll g$ and $g \ll f$. Hence for all $\alpha \in \mathbb{R}^n$ and $v \in \mathbb{R}_+^n$ we also have $f(\alpha + vt) \ll g(\alpha + vt)$ and $g(\alpha + vt) \ll f(\alpha + vt)$. This means that $f(\alpha + vt)$ and $g(\alpha + vt)$ are constant multiples of each other, say $f(\alpha + vt) = \lambda g(\alpha + vt)$. By the multivariate Obreschkoff theorem we have that $f - \lambda g \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$. Since $(f - \lambda g)(\alpha + vi) = 0$ we must have $f - \lambda g \equiv 0$, i.e., $h = (1 + i\lambda)g \in \mathbb{C}\mathcal{H}_n(\mathbb{R})$. \square

Lemma 2.6. *Let $f \in \mathcal{H}_n(\mathbb{R})$. Then the sets*

$$\{g \in \mathcal{H}_n(\mathbb{R}) : f \ll g\} \text{ and } \{g \in \mathcal{H}_n(\mathbb{R}) : f \gg g\}$$

are nonnegative cones, i.e., they are closed under nonnegative linear combinations.

Proof. Let $f \in \mathcal{H}_n(\mathbb{R})$ and suppose that $f \ll g$ and $f \ll h$. Then by Lemma 2.2 we have $\Im(g(z)/f(z)) \geq 0$ and $\Im(h(z)/f(z)) \geq 0$ whenever $\Im(z) > 0$. Hence if $\lambda, \mu \geq 0$ and $\Im(z) > 0$ then $\Im((\lambda g(z) + \mu h(z))/f(z)) \geq 0$ and Lemma 2.2 yields $f \ll \lambda g + \mu h$. The other assertion follows similarly. \square

3. CLASSIFICATIONS OF MULTIVARIATE MULTIPLIER SEQUENCES AND FINITE ORDER ONES

3.1. Univariate and multivariate multiplier sequences. Let us first recall a few well-known properties of (usual) univariate multiplier sequences, see, e.g., [17].

Lemma 3.1. *Let $\lambda : \mathbb{N} \rightarrow \mathbb{R}$ be a multiplier sequence. If $0 \leq i \leq j \leq k$ are such that $\lambda(i)\lambda(k) \neq 0$ then $\lambda(j) \neq 0$. Furthermore, either*

- (i) *all nonzero $\lambda(i)$ have the same sign, or*
- (ii) *all nonzero entries of the sequence $\{(-1)^i \lambda(i)\}_{i \geq 0}$ have the same sign.*

In what follows we denote the standard basis in \mathbb{R}^n by $\{e_k : 1 \leq k \leq n\}$.

Remark 3.1. Suppose that $\alpha \in \mathbb{N}^n$, $1 \leq k \leq n$, $f(z_k) := \sum_{i=0}^N a_i z_k^i \in \mathcal{H}_1(\mathbb{R})$ and assume that λ is a multivariate multiplier sequence. Then

$$T(z^\alpha f(z_k)) = z^\alpha \sum_{i=0}^N \lambda(\alpha + i e_k) a_i z_k^i \in \mathcal{H}_n(\mathbb{R}).$$

Hence the function $i \mapsto \lambda(\alpha + i e_k)$ is a univariate multiplier sequence.

The proofs of our characterizations of multivariate multiplier sequences and those of finite order build on a series of statements that we proceed to describe.

Lemma 3.2. *Let $f(z_1, z_2) = a_{00} + a_{01}z_2 + a_{10}z_1 + a_{11}z_1z_2 \in \mathbb{R}[z_1, z_2] \setminus \{0\}$. Then $f \in \mathcal{H}_2(\mathbb{R})$ if and only if $\det(a_{ij}) \leq 0$.*

Proof. Let $\alpha \in \mathbb{R}$ and denote by $A = (a_{ij})$ the matrix of coefficients of $f(z_1, z_2)$. Clearly, $f(z_1, z_2) \in \mathcal{H}_2(\mathbb{R})$ if and only if $f(z_1 + \alpha, z_2) \in \mathcal{H}_2(\mathbb{R})$ and $f(z_1, z_2 + \alpha) \in \mathcal{H}_2(\mathbb{R})$. We get the matrix corresponding to $f(z_1 + \alpha, z_2)$ by adding α times the last row of A to the first row of A , and we get the matrix corresponding to $f(z_1, z_2 + \alpha)$ by adding α times the last column of A to the first column of A . Since the determinant is preserved under such row and column operations we can assume that A has one of the following forms:

$$\begin{pmatrix} a_{00} & 0 \\ 0 & a_{11} \end{pmatrix}, \quad \begin{pmatrix} 0 & a_{01} \\ a_{10} & 0 \end{pmatrix}, \quad \begin{pmatrix} a_{00} & a_{01} \\ 0 & 0 \end{pmatrix}.$$

Obviously, these matrices correspond to a polynomial $f(z_1, z_2) \in \mathcal{H}_2(\mathbb{R})$ if and only if $\det(a_{ij}) \leq 0$. \square

Lemma 3.3. *Let $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$, $n \geq 2$, be a multivariate multiplier sequence and let $\gamma \in \mathbb{N}^n$ and $1 \leq i < j \leq n$. Then*

$$\lambda(\gamma)\lambda(\gamma + e_i + e_j) = \lambda(\gamma + e_i)\lambda(\gamma + e_j).$$

Proof. Without loss of generality we may assume that $i = 1$ and $j = 2$. Let $f(z) = z^\gamma g(z) \in \mathcal{H}_n(\mathbb{R})$, where $g(z_1, z_2) = a_{00} + a_{01}z_2 + a_{10}z_1 + a_{11}z_1z_2 \in \mathcal{H}_2(\mathbb{R})$. It follows that the polynomial

$$\lambda(\gamma)a_{00} + \lambda(\gamma + e_2)a_{01}z_2 + \lambda(\gamma + e_1)a_{10}z_1 + \lambda(\gamma + e_1 + e_2)a_{11}z_1z_2$$

is stable or identically zero. By choosing A as

$$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix},$$

respectively, we get by Lemma 3.2 that $\lambda(\gamma)\lambda(\gamma + e_1 + e_2) \leq \lambda(\gamma + e_1)\lambda(\gamma + e_2)$ and $\lambda(\gamma)\lambda(\gamma + e_1 + e_2) \geq \lambda(\gamma + e_1)\lambda(\gamma + e_2)$, respectively, which proves the lemma. \square

Given $\alpha, \beta \in \mathbb{N}^n$ with $\alpha \leq \beta$ set $[\alpha, \beta] := \{\gamma \in \mathbb{N}^n : \alpha \leq \gamma \leq \beta\}$.

Lemma 3.4. *Let $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$ be a multivariate multiplier sequence. If $\alpha, \beta \in \mathbb{N}^n$ are such that $\lambda(\alpha)\lambda(\beta) \neq 0$ and $\gamma \in [\alpha, \beta]$ then $\lambda(\gamma) \neq 0$.*

Proof. We use induction on $\ell = |\beta| - |\alpha|$, the length of the interval $[\alpha, \beta]$. The cases $\ell = 0$ and $\ell = 1$ are clear. By Remark 3.1 and Lemma 3.1 the result is true in the univariate case. So we may assume that α and β differ in more than one coordinate, i.e., that $\alpha + e_1, \alpha + e_2 \in [\alpha, \beta]$.

If there exists an atom $\alpha + e_i \in [\alpha, \beta]$ such that $\lambda(\alpha + e_i) \neq 0$ then by induction we have that λ is nonzero in $[\alpha + e_i, \beta]$. If $\alpha + e_j$ is another atom then $\alpha + e_i + e_j \in [\alpha + e_i, \beta]$ so $\lambda(\alpha + e_i + e_j) \neq 0$. Lemma 3.3 then gives that $\lambda(\alpha + e_j) \neq 0$. Thus, by induction, λ is nonzero in $[\alpha + e_j, \beta]$ for all $\alpha + e_j \in [\alpha, \beta]$ and we are done.

In order to get a contradiction we may assume by the above that $\lambda(\alpha + e_i) = 0$ for all $\alpha + e_i \in [\alpha, \beta]$. Let $\gamma \in (\alpha, \beta]$ be a minimal element such that $\lambda(\gamma) \neq 0$. If T is the (diagonal) linear operator associated to λ then

$$T(z^\alpha(1+z)^{\gamma-\alpha}) = \lambda(\alpha)z^\alpha + \lambda(\gamma)z^\gamma \in \mathcal{H}_n(\mathbb{R}).$$

By Lemma 3.3 we have that $\lambda(\alpha + e_i + e_j) = 0$ for all atoms $\alpha + e_i, \alpha + e_j \in [\alpha, \beta]$. By Remark 3.1 and Lemma 3.1 we also have $\lambda(\alpha + me_i) = 0$ for all $m \geq 1$ and atoms $\alpha + e_i \in [\alpha, \beta]$. It follows that $|\gamma| - |\alpha| \geq 3$. Now, if we set $z_i = t$ for all i then by the above we obtain that the polynomial

$$\lambda(\alpha)t^{|\alpha|} + \lambda(\gamma)t^{|\gamma|}$$

is hyperbolic in t , which is a contradiction since $|\gamma| - |\alpha| \geq 3$ and $\lambda(\alpha)\lambda(\gamma) \neq 0$. \square

Lemma 3.5. *Let $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$ be a multivariate multiplier sequence and suppose that $\lambda(\alpha) \neq 0$. Then*

$$\frac{\lambda(\beta)}{\lambda(\alpha)} = \prod_{i=1}^n \frac{\lambda(\alpha + (\beta_i - \alpha_i)e_i)}{\lambda(\alpha)} \quad (4)$$

for all $\beta \geq \alpha$.

Proof. We claim that $\lambda(\gamma)\lambda(\gamma + ae_i + be_j) = \lambda(\gamma + ae_i)\lambda(\gamma + be_j)$ for all $\gamma \in \mathbb{N}^n$ and positive integers a and b . This follows easily by induction on $a + b$ using Lemma 3.3 and Lemma 3.4. We proceed to prove the (4) by induction on the number r of nonzero entries of $\delta = \beta - \alpha$. The basis of induction, $r \leq 1$, is trivial. For $r \geq 2$ let j be an index such that $\delta_j > 0$ and consider $\gamma = \alpha + \delta_j e_j$. By Lemma 3.4 $\lambda(\gamma) \neq 0$. By induction

$$\frac{\lambda(\beta)}{\lambda(\alpha)} = \frac{\lambda(\beta)}{\lambda(\gamma)} \cdot \frac{\lambda(\gamma)}{\lambda(\alpha)} = \prod_{i=1}^n \frac{\lambda(\alpha + (\beta_i - \gamma_i)e_i)}{\lambda(\gamma)} \cdot \frac{\lambda(\alpha + (\gamma_i - \alpha_i)e_i)}{\lambda(\alpha)}.$$

For $i \neq j$ the corresponding factor is

$$\frac{\lambda(\alpha + \delta_i e_i + \delta_j e_j)}{\lambda(\alpha + \delta_j e_j)} \cdot \frac{\lambda(\alpha)}{\lambda(\alpha)} = \frac{\lambda(\alpha + \delta_i e_i)}{\delta(\alpha)}$$

by the claim above. For $i = j$ the corresponding factor is

$$\frac{\lambda(\alpha + \delta_j e_j)}{\lambda(\alpha + \delta_j e_j)} \cdot \frac{\lambda(\alpha + \delta_j e_j)}{\lambda(\alpha)} = \frac{\lambda(\alpha + \delta_j e_j)}{\delta(\alpha)}$$

and the lemma follows by induction. \square

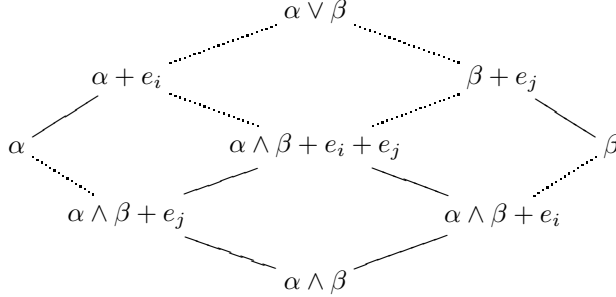


FIGURE 1. Illustration of the induction step in Lemma 3.6.

If $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$ and $\beta = (\beta_1, \dots, \beta_n) \in \mathbb{N}^n$ we define two new vectors $\alpha \vee \beta, \alpha \wedge \beta \in \mathbb{N}^n$ by setting $\alpha \vee \beta = (\max(\alpha_1, \beta_1), \dots, \max(\alpha_n, \beta_n))$ and $\alpha \wedge \beta = (\min(\alpha_1, \beta_1), \dots, \min(\alpha_n, \beta_n))$.

Lemma 3.6. *Let $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$ be a multivariate multiplier sequence and suppose that $\lambda(\alpha)\lambda(\beta) \neq 0$. Then $\lambda(\alpha \vee \beta) \neq 0$ if and only if $\lambda(\alpha \wedge \beta) \neq 0$.*

Proof. If $\lambda(\alpha)\lambda(\beta) \neq 0$ and $\lambda(\alpha \wedge \beta) \neq 0$ then Lemma 3.5 and Lemma 3.1 imply that $\lambda(\alpha \vee \beta) \neq 0$. Suppose that $\lambda(\alpha)\lambda(\beta) \neq 0$ and $\lambda(\alpha \vee \beta) \neq 0$. We prove that $\lambda(\alpha \wedge \beta) \neq 0$ by induction on $|\alpha - \beta|$. If $|\alpha - \beta| = 0$ there is nothing to prove. Also, if α and β are comparable there is nothing to prove, so we may assume that there are indices i and j such that $\alpha_i < \beta_i$ and $\beta_j < \alpha_j$. Since $\alpha < \alpha + e_i \leq \alpha \vee \beta$ and $\beta < \beta + e_j \leq \alpha \vee \beta$ we have by Lemma 3.4 that $\lambda(\alpha + e_i)\lambda(\beta + e_j) \neq 0$. Consider the pairs $(\alpha + e_i, \beta + e_j)$, $(\alpha + e_i, \beta)$ and $(\alpha, \beta + e_j)$. The distance between each of them is smaller than $|\alpha - \beta|$, they all have to join $\alpha \vee \beta$, and the meets are $\alpha \wedge \beta + e_i + e_j$, $\alpha \wedge \beta + e_j$ and $\alpha \wedge \beta + e_i$ respectively, see Fig. 1. By induction we have that $\lambda(\alpha \wedge \beta + e_i)\lambda(\alpha \wedge \beta + e_j)\lambda(\alpha \wedge \beta + e_i + e_j) \neq 0$. By Lemma 3.3 this gives

$$\lambda(\alpha \wedge \beta) = \frac{\lambda(\alpha \wedge \beta + e_i)\lambda(\alpha \wedge \beta + e_j)}{\lambda(\alpha \wedge \beta + e_i + e_j)} \neq 0,$$

which is the desired conclusion. \square

Recall that the *support* of a map $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$ is the set $\{\alpha \in \mathbb{N}^n : \lambda(\alpha) \neq 0\}$.

Lemma 3.7. *Let $\lambda : \mathbb{N}^n \rightarrow \mathbb{R}$ be a multivariate multiplier sequence. Then there exist univariate multiplier sequences $\lambda_i : \mathbb{N} \rightarrow \mathbb{R}$, $1 \leq i \leq n$, such that*

$$\lambda(\alpha) = \lambda_1(\alpha_1)\lambda_2(\alpha_2) \cdots \lambda_n(\alpha_n), \quad \alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n.$$

Proof. Let S be the support of λ . By Lemma 3.5 and Remark 3.1 it suffices to prove that S has a unique minimal element. So far, by Lemma 3.4 and Lemma 3.6 we know that S is a disjoint union $S = \cup_{i=1}^m B_i$ of boxes $B_i = I_1^i \times \cdots \times I_n^i$, where I_n^i is an interval (possibly infinite) of nonnegative integers. Also, points in different boxes are incomparable.

Suppose that S does not have a unique minimal element. We claim that there exists an interval $[\alpha, \beta]$ such that $[\alpha, \beta] \cap S = \{\delta, \gamma\}$, where δ and γ are in different boxes. We postpone the proof of this statement for a while and show first how it

leads to a contradiction. Let T be the (diagonal) linear operator associated to λ . We then have

$$T(z^\alpha(1+z)^{\beta-\alpha}) = \lambda(\delta)z^\delta + \lambda(\gamma)z^\gamma.$$

Now $|\delta - \gamma| \geq 3$ since otherwise δ and γ would be comparable or we would have $\gamma = \delta \wedge \gamma + e_i$ and $\delta = \delta \wedge \gamma + e_j$ for some i and j . This is impossible by Lemma 3.3 since γ and δ would then be in the same box. By assumption we have that

$$\lambda(\delta)z^{\delta-\delta \wedge \gamma} + \lambda(\gamma)z^{\gamma-\delta \wedge \gamma} \in \mathcal{H}_n(\mathbb{R})$$

so by setting all the variables in $z^{\delta-\delta \wedge \gamma}$ equal to t and setting all the variables in $z^{\gamma-\delta \wedge \gamma}$ equal to $-t^{-1}$ (which we may since $z^{\delta-\delta \wedge \gamma}$ and $z^{\gamma-\delta \wedge \gamma}$ contain no common variables) we obtain that

$$\lambda(\delta)t^{|\delta-\gamma|} \pm \lambda(\gamma) \in \mathcal{H}_1(\mathbb{R}).$$

This is a contradiction since $|\delta - \gamma| \geq 3$ and $\delta, \gamma \in S$ so $\lambda(\delta)\lambda(\gamma) \neq 0$.

It remains to prove the claim. Let d be the minimal distance between different boxes and suppose that δ and γ are two points that realize the minimal distance. If $\kappa \in [\delta \wedge \gamma, \delta \vee \gamma]$ then $|\kappa - \delta| \leq d$ with equality only if $\kappa = \gamma$ and $|\kappa - \gamma| \leq d$ with equality only if $\kappa = \delta$. It follows that $[\delta \wedge \gamma, \delta \vee \gamma] \cap S = \{\delta, \gamma\}$. \square

3.2. Affine differential contractions and multivariate compositions. For the proof of Theorem 1.8 we need to establish first Theorem 3.11 below, which is the main purpose of this section.

The proof of Theorem 3.11 relies on some of the results obtained in [39]. Let us introduce the following notation. Given $a, b \in \mathbb{C}$, $1 \leq i < j \leq n$ and

$$F(z_1, \dots, z_n) = \sum_{\alpha \in \mathbb{N}^n} a_\alpha z^\alpha \in \mathbb{C}[z_1, \dots, z_n]$$

let

$$F\left(z_1, \dots, z_{i-1}, az_i + b \frac{\partial}{\partial z_j}, z_{i+1}, \dots, z_j, \dots, z_n\right) \quad (5)$$

denote the polynomial

$$\sum_{\alpha \in \mathbb{N}^n} a_\alpha z_1^{\alpha_1} \cdots z_{i-1}^{\alpha_{i-1}} \left(az_i + b \frac{\partial}{\partial z_j}\right)^{\alpha_i} z_{i+1}^{\alpha_{i+1}} \cdots z_j^{\alpha_j} \cdots z_n^{\alpha_n}.$$

The next lemma follows from [39, Lemma 2.3] by a rotation of the variables.

Lemma 3.8 ([39]). *If $P_0(v), P_1(v) \in \mathbb{C}[v]$ with $P_0(v) + xP_1(v) \neq 0$ for $\Im(v) \geq c$ and $\Im(x) \geq d$ then*

$$P_0(v) + \left(x - \frac{\partial}{\partial v}\right) P_1(v) \neq 0$$

for $\Im(v) \geq c$ and $\Im(x) \geq d$.

Using Lemma 3.8 and the Grace-Walsh-Szegő Coincidence Theorem [51] one can argue as in the proof of [39, Proposition 2.2] to show:

Proposition 3.9 ([39]). *Let $(c_1, \dots, c_n) \in \mathbb{R}^n$ and $F \in \mathbb{C}[z_1, \dots, z_n]$ be such that*

$$F(z_1, \dots, z_n) \neq 0$$

if $\Im(z_k) \geq c_k$, $1 \leq k \leq n$. Then for any $1 \leq i < j \leq n$ one has

$$F\left(z_1, \dots, z_{i-1}, z_i - \frac{\partial}{\partial z_j}, z_{i+1}, \dots, z_j, \dots, z_n\right) \neq 0$$

whenever $\Im(z_k) \geq c_k$, $1 \leq k \leq n$.

From Proposition 3.9 we immediately get the following.

Corollary 3.10 ([39]). *Suppose that $1 \leq i < j \leq n$ and $F(z_1, \dots, z_n) \in \mathcal{H}_n(\mathbb{C})$. Then $F(z_1, \dots, z_{i-1}, -\partial_j, z_{i+1}, \dots, z_j, \dots, z_n) \in \mathcal{H}_{n-1}(\mathbb{C}) \cup \{0\}$.*

We can now prove the following extension of a famous composition theorem of Schur [54] and related results of Maló-Szegő [17, 51] to the multivariate case. Further consequences of Theorem 3.11 will be given in Section 4.3 and Section 4.4.

Theorem 3.11. *Assume that all the zeros of $f(z) = \sum_{i=0}^r a_i z^i \in \mathcal{H}_1(\mathbb{R})$ are non-positive and that $F(z_1, \dots, z_n) = \sum_{j=0}^s Q_j(z_2, \dots, z_n) z_1^j \in \mathcal{H}_n(\mathbb{C})$ and set $m = \min(r, s)$. Then*

$$\sum_{k=0}^m k! a_k Q_k(z_2, \dots, z_n) z_1^k \in \mathcal{H}_n(\mathbb{C}) \cup \{0\}.$$

Proof. Suppose that f has only nonpositive zeros. Then $f(-z_0 w_0) \in \mathcal{H}_2(\mathbb{R})$ so that

$$G(w_0, z_0, \dots, z_n) := f(-z_0 w_0) F(z_1, \dots, z_n) \in \mathcal{H}_{n+2}(\mathbb{C}).$$

By Corollary 3.10 we have that

$$H(z_0, z_1, \dots, z_n) := G\left(-\frac{\partial}{\partial z_1}, z_0, \dots, z_n\right) \in \mathcal{H}_{n+1}(\mathbb{C}) \cup \{0\}.$$

This means that

$$H(z_1, 0, z_2, \dots, z_n) = \sum_{k=0}^m k! a_k Q_k(z_2, \dots, z_n) z_1^k \in \mathcal{H}_n(\mathbb{C}) \cup \{0\},$$

as required. \square

3.3. Proofs of Theorems 1.8 and 1.9. We can now settle the classification of multivariate multiplier sequences stated in Theorem 1.8.

of Theorem 1.8. For the “only if” direction what remains to be proven is the statement about the signs. If it were false for some (multivariate) multiplier sequence λ then since λ is a product of univariate multiplier sequences whose entries either all have the same sign or alternate in sign there would exist $\alpha \in \mathbb{N}^n$ such that $\lambda(\alpha) \neq 0$ and $\lambda(\alpha + e_i) \lambda(\alpha + e_j) < 0$. Let T be the corresponding (diagonal) operator and apply it to $z^\alpha (1 - z_i z_j) \in \mathcal{H}_n(\mathbb{R})$. By Lemma 3.3 we get

$$T(z^\alpha (1 - z_i z_j)) = \lambda(\alpha) z^\alpha \left(1 - \frac{\lambda(\alpha + e_i) \lambda(\alpha + e_j)}{\lambda(\alpha)^2} z_i z_j\right).$$

Since $1 + a z_1 z_2 \in \mathcal{H}_2(\mathbb{R})$ if and only if $a \leq 0$ this is a contradiction.

Now $\alpha \mapsto \lambda(\alpha)$ is a multiplier sequence if and only if $\alpha \mapsto (-1)^{|\alpha|} \lambda(\alpha)$ is a multiplier sequence so we may assume that $\lambda(\alpha) \geq 0$ for all $\alpha \in \mathbb{N}^n$. By applying the λ_i 's one at a time we may further assume that $\lambda_i \equiv 1$ for $2 \leq i \leq n$. Hence we have to show that if $f(z_1, \dots, z_n) := \sum_{i=0}^M Q_i(z_2, \dots, z_n) z_1^i \in \mathcal{H}_n(\mathbb{R})$ and $\lambda : \mathbb{N} \rightarrow \mathbb{R}$ is a nonnegative univariate multiplier sequence then

$$\sum_{i=0}^M \lambda(i) Q_i(z_2, \dots, z_n) z_1^i \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}.$$

By Theorem 1.7 there are polynomials

$$p_k(z) = \sum_{i=0}^{N_k} \frac{\lambda_{i,k}}{i!} z^i, \quad k \in \mathbb{N},$$

with only nonpositive zeros and

$$\lim_{k \rightarrow \infty} p_k(z) = \sum_{i=0}^{\infty} \frac{\lambda(i)}{i!} z^i.$$

Furthermore, by Theorem 3.11 we know that

$$\sum_{i=0}^M \lambda_{i,k} Q_i(z_2, \dots, z_n) z_1^i \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$$

for each k . Since $\lim_{k \rightarrow \infty} \lambda_{i,k} = \lambda(i)$ we get $\sum_{i=0}^M \lambda(i) Q_i(z_2, \dots, z_n) z_1^i \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ by Lemma 2.3, which settles the theorem. \square

Let us finally prove the characterization of finite order multiplier sequences.

of Theorem 1.9. The “if” direction is an immediate consequence of Theorem 1.3, the proof of which is given in Section 4 below. To prove the converse statement note first that Theorem 1.8 implies that the symbol of T is the product of the symbols of the corresponding univariate operators. Hence it suffices to settle the case $n = 1$. Let $F(z, w) = \sum_{k=0}^N a_k z^k w^k$ be the symbol of T . By Theorem 1.7 we know that all zeros of

$$g_m(z) = T[(1+z)^m] = \sum_{k=0}^M a_k(m)_k z^k (1+z)^{m-k}$$

are real and have the same sign. Note that these zeros are actually nonpositive since $z = -1$ is a zero of $g_m(z)$ for all large m . Now

$$g_m(z/m) = \left(1 + \frac{z}{m}\right)^m \sum_{k=0}^M a_k \frac{(m)_k}{m^k} z^k (1+z/m)^{-k}$$

and since $\lim_{m \rightarrow \infty} \frac{(m)_k}{m^k} = 1$ we have

$$\lim_{m \rightarrow \infty} g_m(z/m) = e^z \sum_{k=0}^M a_k z^k.$$

Hence by Lemma 2.3 the polynomial $\sum_{k=0}^M a_k z^k$ has all nonpositive zeros and the theorem follows. \square

4. ALGEBRAIC AND GEOMETRIC PROPERTIES OF STABILITY PRESERVERS

4.1. Sufficiency in Theorems 1.2 and 1.3. Since $\mathcal{H}_n(\mathbb{R}) \subset \mathcal{H}_n(\mathbb{C})$ it is enough to prove only the sufficiency in Theorem 1.2. Recall the “affine differential contraction” of a polynomial $F \in \mathbb{C}[z_1, \dots, z_n]$ defined in (5) and note that the following consequence of Corollary 3.10 actually settles the sufficiency part in Theorem 1.2.

Corollary 4.1. *Let $T \in \mathcal{A}_n[\mathbb{C}]$ and suppose that $F_T(z, -w) \in \mathcal{H}_{2n}(\mathbb{C})$. Then $T \in \mathcal{A}_n(\mathbb{C})$.*

Proof. If $F_T(z, -w) \in \mathcal{H}_{2n}(\mathbb{C})$ and $f(v) \in \mathcal{H}_n(\mathbb{C})$ then $F_T(z, -w)f(v) \in \mathcal{H}_{3n}(\mathbb{C})$. By Corollary 3.10 if we exchange the variables w_i 's for $-\partial/\partial v_i$'s the resulting polynomial will be in $\mathcal{H}_{2n}(\mathbb{C}) \cup \{0\}$. If we then replace each variable v_i with z_i for all $1 \leq i \leq n$, we get a polynomial in $\mathcal{H}_n(\mathbb{C}) \cup \{0\}$. This polynomial is indeed $T(f)$. \square

4.2. Necessity in Theorems 1.2 and 1.3. Let $T = \sum_{\alpha, \beta} a_{\alpha, \beta} z^\alpha \partial^\beta \in \mathcal{A}_n[\mathbb{R}]$. We may write T as a finite sum $T = \sum_{\gamma \in \mathbb{Z}^n} z^\gamma T_\gamma$, where $T_\gamma = \sum_{\beta} a_{\gamma+\beta, \beta} z^\beta \partial^\beta$. It follows that T_γ acts on monomials as $T_\gamma(z^\alpha) = \lambda_\gamma(\alpha) z^\alpha$ for some function $\lambda_\gamma : \mathbb{N}^n \rightarrow \mathbb{R}$. The following lemma gives a sufficient condition for λ_γ to be a multiplier sequence.

Lemma 4.2. *Let $T = \sum_{\gamma} z^\gamma T_\gamma \in \mathcal{A}_n(\mathbb{R})$ and denote by $CH(T)$ the convex hull of the set $\{\gamma : T_\gamma \neq 0\}$. If $\kappa \in \mathbb{Z}^n$ is a vertex (face of dimension 0) of $CH(T)$ then T_κ is a multiplier sequence.*

Proof. Let $v \in \mathbb{R}_+^n$. If $f(z) \in \mathcal{H}_n(\mathbb{R})$ then $f(vz) = f(v_1 z_1, \dots, v_n z_n) \in \mathcal{H}_n(\mathbb{R})$ and

$$T[f(vz)] = \sum_{\alpha, \beta} a_{\alpha, \beta} z^\alpha v^\beta (\partial^\beta f)(vz).$$

Hence

$$T^v := \sum_{\alpha, \beta} a_{\alpha, \beta} v^{\alpha-\beta} z^\alpha \partial^\beta = \sum_{\gamma} v^\gamma z^\gamma T_\gamma \in \mathcal{A}_n(\mathbb{R}).$$

Let $\langle z, \mu \rangle = a$ be a supporting hyperplane of the vertex κ . Hence, up to replacing μ with $-\mu$, if necessary, we have $\langle \gamma - \kappa, \mu \rangle < 0$ for all $\gamma \in CH(T) \setminus \{\kappa\}$. Now let $v_i = v_i(t) = e^{\mu_i t}$. Then

$$v^{-\kappa} T^v = z^\kappa T_\kappa + \sum_{\gamma \neq \kappa} e^{t \langle \gamma - \kappa, \mu \rangle} z^\gamma T_\gamma.$$

By letting $t \rightarrow \infty$ we have that $z^\kappa T_\kappa \in \mathcal{A}_n(\mathbb{R})$ and the lemma follows. \square

Let $f = \sum_{\alpha} a(\alpha) z^\alpha \in \mathbb{R}[z_1, \dots, z_n]$. Define the *support* $\text{supp}(f)$ of f to be the set $\{\alpha \in \mathbb{N}^n : a(\alpha) \neq 0\}$ and let $d = \max\{|\alpha| : \alpha \in \text{supp}(f)\}$. We further define the *leading part* of f to be $a(\alpha) z^\alpha$, where α is the maximal element of the set $\{\gamma \in \text{supp}(f) : |\gamma| = d\}$ with respect to the lexicographic order on \mathbb{Z}^n . Similarly, if $T = \sum_{\gamma} z^\gamma T_\gamma \in \mathcal{A}_n[\mathbb{R}]$ let $k = \max\{|\alpha| : T_\alpha \neq 0\}$ and let κ_0 be the maximal element of the set $\{\alpha : |\alpha| = k, T_\alpha \neq 0\}$ with respect to the lexicographical order. Since κ_0 is a vertex of $CH(T)$ we know that λ_{κ_0} is a multiplier sequence with a finite symbol whenever $T \in \mathcal{A}_n(\mathbb{R})$. We say that T_{κ_0} is the *dominating part* of T . Note that the dominating part of fg is the product of the dominating parts of f and g . Moreover, if $\lambda_{\kappa_0}(\alpha) \neq 0$ then the dominating part of $T(f)$ is $\lambda_{\kappa_0}(\alpha) a(\alpha) z^{\alpha+\kappa_0}$, where $a(\alpha) z^\alpha$ is the dominating part of f and T_{κ_0} is the dominating part of T .

We are now ready to prove that a real stability preserver also preserves proper position. Equivalently, Theorem 4.3 below asserts that $\mathcal{A}_n(\mathbb{R}) \subset \mathcal{A}_n(\mathbb{C})$.

Theorem 4.3. *Suppose that $T \in \mathcal{A}_n(\mathbb{R})$ and that $f, g \in \mathcal{H}_n(\mathbb{R})$ are such that $f \ll g$. Then either $T(f) \ll T(g)$ or $T(f) = T(g) \equiv 0$.*

Proof. Let T_{κ_0} be the dominating part of T . We first assume that $f = \sum_{\alpha} a_{\alpha} z^{\alpha}$, $g = \sum_{\alpha} b_{\alpha} z^{\alpha} \in \mathcal{H}_n(\mathbb{R})$ are such that $f \ll g$, $0 \leq \deg(f) < \deg(g)$ and $T_{\kappa_0}(f)T_{\kappa_0}(g) \neq 0$.

Let the leading parts of f and g be $a(\alpha)z^\alpha$ and $b(\beta)z^\beta$, respectively. Let

$$f_H = \sum_{|\alpha|=\deg(f)} a_\alpha z^\alpha \quad \text{and} \quad g_H = \sum_{|\alpha|=\deg(g)} b_\alpha z^\alpha.$$

By Hurwitz' theorem f_H and g_H are stable. Moreover all coefficients is f_H (and in g_H) have the same sign by [16, Theorem 6.1]. Consider $f(vt), g(vt) \in \mathcal{H}_1(\mathbb{R})$ where $v \in \mathbb{R}_+^n$. Then $\deg g(vt) = \deg f(vt) + 1$ and the signs of the leading coefficients of $g(vt)$ and $f(vt)$ will be the same as the signs of $b(\beta)$ and $a(\alpha)$, respectively. Since also $f(vt) \ll g(vt)$ we infer that $a(\alpha)b(\beta) > 0$.

Now since $T_{\kappa_0}(f)T_{\kappa_0}(g) \neq 0$ it follows that the leading parts of $T(f)$ and $T(g)$ are $\lambda_{\kappa_0}(\alpha)a(\alpha)z^{\kappa_0+\alpha}$ and $\lambda_{\kappa_0}(\beta)b(\beta)z^{\kappa_0+\beta}$, respectively. By Theorem 1.6 (the multivariate Obreschkoff theorem) we know that either $T(f) \ll T(g)$ or $T(g) \ll T(f)$. As pointed out in the paragraph preceding Theorem 4.3 dominating parts are necessarily multivariate multiplier sequences and so by Theorem 1.9 we have that $\lambda_{\kappa_0}(\alpha)\lambda_{\kappa_0}(\beta) > 0$. From the above discussion it follows that for $v \in \mathbb{R}_+^n$ we have $T(f)(vt) \ll T(g)(vt)$ with $\deg(T(f)(vt)) < \deg(T(g)(vt))$, so that $T(f) \ll T(g)$.

If $\deg(f) > \deg(g)$ we may simply repeat the arguments using $-f$ and g . If $\deg(f) = \deg(g)$ we consider f and $g + \epsilon z_1 f$ with $\epsilon > 0$. Indeed, $\deg(f) < \deg(g + \epsilon z_1 f)$ and $f \ll g + \epsilon z_1 f$ by Lemma 2.6. We then apply the argument of the first case, and obtain the desired conclusion as $\epsilon \rightarrow 0$.

Suppose now that $T_{\kappa_0}(f)T_{\kappa_0}(g) = 0$. There is nothing to prove if $fg \equiv 0$. Let $h_\epsilon(z_1, \dots, z_n) = (1 + \epsilon z_1)^{\xi_1} \cdots (1 + \epsilon z_n)^{\xi_n}$ with $\xi_i \in \mathbb{N}$, $1 \leq i \leq n$, and let $f_\epsilon = h_\epsilon f$ and $g_\epsilon = h_\epsilon g$. If $\xi = (\xi_1, \dots, \xi_n)$ is large enough then $T_{\kappa_0}(f_\epsilon)T_{\kappa_0}(g_\epsilon) \neq 0$. The theorem follows from Lemma 2.3 by letting $\epsilon \rightarrow 0$. \square

For the proof of necessity in Theorems 1.2 and 1.3 we need to establish first a key property for symbols of (real) stability preservers.

Lemma 4.4. *Suppose that $F(z, w) \in \mathbb{R}[z_1, \dots, z_n, w_1, \dots, w_n]$ is the symbol of an operator in $\mathcal{A}_n(\mathbb{R})$ and let $\lambda \in (0, 1)^n$. Then $F(z, \lambda w)$ is also the symbol of an operator in $\mathcal{A}_n(\mathbb{R})$.*

Proof. Suppose that $T \in \mathcal{A}_n(\mathbb{R})$ has symbol $F(z_1, \dots, z_n, w_1, \dots, w_n)$. We claim that if $\delta \geq 0$ then the linear operator $\mathcal{E}_1^\delta T$ defined by

$$\mathcal{E}_1^\delta T(f) = \sum_{m=0}^{\infty} \frac{\delta^m z_1^m T(\partial_1^m f)}{m!}$$

is an operator $\mathcal{E}_1^\delta T : \mathcal{H}_n(\mathbb{R}) \rightarrow \mathcal{H}_n(\mathbb{R}) \cup \{0\}$. If T_δ is the linear operator with symbol $F(z_1, \dots, z_n, w_1/(1 + \delta), \dots, w_n)$ then a simple calculation shows that

$$T_\delta(f) = \mathcal{E}_1^\delta T(f(z_1(1 + \delta), \dots, z_n)).$$

Hence the claim would prove the lemma.

In order to prove the remaining claim let $\delta \geq 0$ and define a linear operator $R_\delta T : \mathbb{R}[z_1, \dots, z_n] \rightarrow \mathbb{R}[z_1, \dots, z_n]$ by

$$R_\delta T(f) = T(f) + \delta z_1 T(\partial_1 f).$$

Suppose that $f \in \mathcal{H}_n(\mathbb{R})$ and that $T(\partial_1 f) \neq 0$. Since $1 - iw_1 \in \mathcal{H}_n(\mathbb{C})$ we know by Corollary 4.1 that $1 + i\partial_1 \in \mathcal{A}_n(\mathbb{C})$, so $f + i\partial_1 f \in \mathcal{H}_n(\mathbb{C})$, i.e., $\partial_1 f \ll f$. By Theorem 4.3 we know that $T(\partial_1 f) \ll T(f)$ and $T(\partial_1 f) \ll z_1 T(\partial_1 f)$, which by Lemma 2.6 gives $R_\delta T(f) \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$. If $T(\partial_1 f) = 0$ then $R_\delta T(f) = T(f) \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}$, so $R_\delta T \in \mathcal{A}_n(\mathbb{R})$.

An elementary computation shows that when we apply R_δ to T m times we get

$$R_\delta^m T(f) = \sum_{k=0}^m \binom{m}{k} \delta^k z_1^k T(\partial_1^k f).$$

By induction, $R_{\delta/m}^m : \mathcal{H}_n(\mathbb{R}) \rightarrow \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ for all $m \in \mathbb{N}$. Now

$$\begin{aligned} R_{\delta/m}^m T(f) &= \sum_{k=0}^m \binom{m}{k} m^{-k} \delta^k z_1^k T(\partial_1^k f) \\ &= \sum_{k=0}^m \left(1 - \frac{1}{m}\right) \left(1 - \frac{2}{m}\right) \cdots \left(1 - \frac{k-1}{m}\right) \frac{\delta^k z_1^k T(\partial_1^k f)}{k!}. \end{aligned}$$

It follows that $R_{\delta/m}^m T(f)$ tends uniformly to $\mathcal{E}^\delta T(f)$ on any compact subset of \mathbb{C}^n as $m \rightarrow \infty$. Thus $\mathcal{E}^\delta T : \mathcal{H}_n(\mathbb{R}) \rightarrow \mathcal{H}_n(\mathbb{R}) \cup \{0\}$ by Lemma 2.3. \square

From Lemma 4.4 one can easily see that symbols of (real) stability preservers actually satisfy the following homotopical property:

Theorem 4.5. *If $F(z, w) \in \mathbb{R}[z_1, \dots, z_n, w_1, \dots, w_n]$ is the symbol of an operator in $\mathcal{A}_n(\mathbb{R})$ then $F(\mu z, \lambda w)$ is also the symbol of an operator in $\mathcal{A}_n(\mathbb{R})$ for any $(\mu, \lambda) \in [0, 1]^n \times [0, 1]^n$. Moreover, the corresponding statement holds for symbols of operators in $\mathcal{A}_n(\mathbb{C})$.*

We now have all the tools to accomplish the proof of the necessity in Theorem 1.3.

of Theorem 1.3. The final step in the proof is to show that $F(z, \mu z^{-1}) \neq 0$ whenever F is the symbol of an operator $T \in \mathcal{A}_n(\mathbb{R})$, $\mu \in \mathbb{R}_+^n$ and $z = (z_1, \dots, z_n) \in \mathbb{C}^n$ is such that $\Im(z_i) > 0$ for all $1 \leq i \leq n$. Indeed, since $F(z, w)$ is the symbol of a real stability preserver if and only if $F(z + \alpha, w)$ is the symbol of a real stability preserver for all $\alpha \in \mathbb{R}^n$ the claim implies that $F(z + \alpha, \mu z^{-1}) \neq 0$ whenever F is the symbol of an operator $T \in \mathcal{A}_n(\mathbb{R})$, $\alpha \in \mathbb{R}^n$, $\mu \in \mathbb{R}_+^n$ and $z \in \mathbb{C}^n$ is such that $\Im(z_i) > 0$ for $1 \leq i \leq n$. But it is straightforward to see that any pair $Z, W \in \mathbb{C}^n$ such that $\Im(Z_i) > 0$ and $\Im(W_i) < 0$ can be written as $Z_i = \alpha_i + z_i$ and $W_i = \mu_i z_i^{-1}$, where $\Im(z_i) > 0$, $\alpha_i \in \mathbb{R}$ and $\mu_i > 0$ for all $1 \leq i \leq n$. Thus, the theorem follows from this claim.

Let $T = \sum_{\alpha, \beta} a_{\alpha\beta} z^\alpha \partial^\beta \in \mathcal{A}_n(\mathbb{R})$ and let F be its symbol. By multiplying with a large monomial we may assume that $a_{\alpha\beta} = 0$ if $\alpha \not\geq \beta$. Let $v \in \mathbb{R}_+^n$ and denote by ${}^v T$ the operator with symbol $F(z, vw)$. By Lemma 4.4 we have that

$$\begin{aligned} {}^v T(z^\gamma) z^{-\gamma} &= \sum_{\alpha, \beta} a_{\alpha\beta} v^\beta z^{\alpha-\beta} (\gamma)_\beta \\ &= \sum_{\alpha, \beta} a_{\alpha\beta} (v\gamma)^\beta z^{\alpha-\beta} (\gamma)_\beta \gamma^{-\beta} \in \mathcal{H}_n(\mathbb{R}) \cup \{0\} \end{aligned}$$

for all $v \in (0, 1)^n$. Fix $\mu \in \mathbb{R}_+^n$ and let v in the above equation be of the form $\mu\gamma^{-1}$ with $\gamma = (\gamma_1, \dots, \gamma_n) \in \mathbb{N}^n$, where $\gamma^{-1} = (\gamma_1^{-1}, \dots, \gamma_n^{-1})$. Then $v \in (0, 1)^n$ for large γ . Letting γ tend to infinity and observing that $(\gamma)_\beta \gamma^{-\beta} \rightarrow 1$ we find by Lemma 2.3 that

$$\sum_{\alpha, \beta} a_{\alpha\beta} \mu^\beta z^{\alpha-\beta} = F(z, \mu z^{-1}) \in \mathcal{H}_n(\mathbb{R}) \cup \{0\}.$$

We have to prove that $F(z, \mu z^{-1})$ is not identically zero. To do this observe that

$$F(z, \mu z^{-1}) = \sum_{\kappa} z^{\kappa} \sum_{\beta} a_{\beta+\kappa, \beta} \mu^{\beta}.$$

By Lemma 4.2 the dominating part, $T_{\kappa_0} = \sum_{\beta} a_{\beta+\kappa_0, \beta} z^{\beta} \partial^{\beta}$, of T is an operator associated to a multiplier sequence with finite symbol. Hence the nonzero coefficients $a_{\beta+\kappa_0, \beta}$ are all of the same sign by Theorem 1.9. This means that the coefficient of z^{κ_0} in $F(z, \mu z^{-1})$ is nonzero and proves the theorem. \square

The proof of necessity in Theorem 1.2 now follows easily.

of Theorem 1.2. Let $T \in \mathcal{A}_n(\mathbb{C})$ and write the symbol of T as $F(z, w) = F_R(z, w) + iF_I(z, w)$, where $F_R(z, w)$ and $F_I(z, w)$ have real coefficients. Let further T_R and T_I be the corresponding operators. Now $T : \mathcal{H}_n(\mathbb{R}) \rightarrow \mathcal{H}_n(\mathbb{C}) \cup \{0\}$ so by Lemma 2.2 we have that $T_R + z_{n+1}T_I : \mathcal{H}_n(\mathbb{R}) \rightarrow \mathcal{H}_{n+1}(\mathbb{R}) \cup \{0\}$. Hence by Lemma 2.1 we know that $T_R + (\lambda z_1 + \alpha)T_I \in \mathcal{A}_n(\mathbb{R}) \cup \{0\}$ for every $\lambda \in \mathbb{R}_+$ and $\alpha \in \mathbb{R}$. Suppose that $T_R + (\lambda z_1 + \alpha)T_I = 0$. Then $T = (i - \alpha - \lambda z_1)T_I$, so $T_I = 0$ since $i - \alpha - \lambda z_1 \notin \mathcal{H}_1(\mathbb{C})$. We thus have $T_R + (\lambda z_1 + \alpha)T_I \in \mathcal{A}_n(\mathbb{R})$ for every $\lambda \in \mathbb{R}_+$ and $\alpha \in \mathbb{R}$, which by Theorem 1.3 gives $F_R + (\lambda z_1 + \alpha)F_I \in \mathcal{H}_n(\mathbb{R})$ for every $\lambda \in \mathbb{R}_+$ and $\alpha \in \mathbb{R}$. By Lemma 2.1 and Lemma 2.2 this implies that $F = F_R + iF_I \in \mathcal{H}_n(\mathbb{C})$, as was to be shown. \square

4.3. The Weyl product and Schur-Maló-Szegő type theorems. The results of Section 3.2 provide a unifying framework for most of the classical composition theorems for univariate hyperbolic polynomials [17, 41, 51, 54]. Moreover, they lead to natural multivariate extensions of these composition theorems. Let us for instance consider two operators $S, T \in \mathcal{A}_n[\mathbb{C}]$ with symbols $F_S(z, w)$ and $F_T(z, w)$, respectively. The well-known product formula in the Weyl algebra [6] asserts that the symbol of the composite operator ST is given by

$$F_{ST}(z, w) = \sum_{\kappa \in \mathbb{N}^n} \frac{1}{\kappa!} \partial_w^{\kappa} F_S(z, w) \partial_z^{\kappa} F_T(z, w). \quad (6)$$

This suggests the following definition.

Definition 4.1. Let $z = (z_1, \dots, z_n)$, $w = (w_1, \dots, w_n)$. The Weyl product of two polynomials $f(z, w), g(z, w) \in \mathbb{C}[z, w]$ is given by

$$(f \star g)(z, w) = \sum_{\kappa \in \mathbb{N}^n} \frac{(-1)^{|\kappa|}}{\kappa!} \partial_z^{\kappa} f(z, w) \partial_w^{\kappa} g(z, w).$$

Theorems 1.2 and 1.3 and (6) imply that the Weyl product of polynomials defined above preserves (real) stability:

Theorem 4.6. *If $f(z, w)$ and $g(z, w)$ are (real) stable polynomials in the variables z_1, \dots, z_n and w_1, \dots, w_n then their Weyl product $(f \star g)(z, w)$ is also (real) stable.*

Example 4.1 ((Schur-Maló-Szegő theorem)). Suppose that $S, T \in \mathcal{A}_1[\mathbb{R}]$ are such that $F_S(z, w) = f(\lambda^{-1}zw)$ and $F_T(z, w) = g(\lambda z)$, where $f \in \mathcal{H}_1(\mathbb{R})$ has only nonpositive zeros, $g \in \mathcal{H}_1(\mathbb{R})$ and $\lambda > 0$. Then $S, T \in \mathcal{A}_1(\mathbb{R})$ by Theorem 1.3. Hence $ST \in \mathcal{A}_1(\mathbb{R})$ and therefore

$$F_{ST}(z, -w) = \sum_{k \geq 0} \frac{1}{k!} z^k f^{(k)}(-\lambda^{-1}zw) g^{(k)}(\lambda z) \in \mathcal{H}_2(\mathbb{R})$$

by (6). Letting $w = 0$ and $\lambda \rightarrow 0$ it follows that

$$\sum_{k \geq 0} k! \frac{f^{(k)}(0)}{k!} \frac{g^{(k)}(0)}{k!} z^k \in \mathcal{H}_1(\mathbb{R}),$$

which is a well-known result of Schur [54], Maló and Szegő [17, 51].

From Theorem 4.6 one can also recover de Bruijn's composition results [12, 13]. As for composition (or Hadamard-Schur convolution) theorems in the multivariate case, we should point out that in [31] Hinkkanen obtained such a result for multi-affine polynomials – i.e., multivariate polynomials of degree at most one in each variable – that are nonvanishing when all variables lie in the open unit disk \mathbf{D} . Note that in the case of the open upper half-plane Theorem 4.6 generalizes Hinkkanen's composition theorem to arbitrary (not necessarily multi-affine) stable polynomials. In fact, by an appropriate conformal transformation one can obtain an analog of Theorem 4.6 for multivariate polynomials of arbitrary degrees that are nonvanishing when all variables are in \mathbf{D} , thus extending Hinkkanen's convolution theorem.

Finally, by using Theorems 1.2 and 1.3 we can derive yet another property of (real) stability preservers:

Proposition 4.7. *Let $T \in \mathcal{A}_n[\mathbb{C}]$ with $F_T(z, w) = \sum_{\alpha \in \mathbb{N}^n} Q_\alpha(z) w^\alpha$, where as before $z = (z_1, \dots, z_n)$ and $w = (w_1, \dots, w_n)$. If $T \in \mathcal{A}_n(\mathbb{C})$ (respectively, $\mathcal{A}_n(\mathbb{R})$) then $Q_\alpha(z) \in \mathcal{H}_n(\mathbb{C}) \cup \{0\}$ (respectively, $\mathcal{H}_n(\mathbb{R}) \cup \{0\}$) for all $\alpha \in \mathbb{N}^n$.*

Proof. If $T \in \mathcal{A}_n(\mathbb{C})$, then $F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \in \mathcal{H}_{2n}(\mathbb{C})$ by Theorem 1.2. It follows that for any polynomial $P(v_1, \dots, v_n) \in \mathcal{H}_n(\mathbb{C})$ one has

$$P(v_1, \dots, v_n) F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \in \mathcal{H}_{3n}(\mathbb{C})$$

hence

$$P\left(-\frac{\partial}{\partial w_1}, \dots, -\frac{\partial}{\partial w_n}\right) F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \in \mathcal{H}_{2n}(\mathbb{C}) \cup \{0\}$$

by Corollary 3.10. Now the polynomial $P_\alpha(v_1, \dots, v_n) := v_1^{\alpha_1} \dots v_n^{\alpha_n}$ clearly belongs to $\mathcal{H}_n(\mathbb{C})$ for any $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$, so that by the above one has

$$\alpha! Q_\alpha(z) = P_\alpha\left(-\frac{\partial}{\partial w_1}, \dots, -\frac{\partial}{\partial w_n}\right) F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \Big|_{w_1 = \dots = w_n = 0} \in \mathcal{H}_n(\mathbb{C}) \cup \{0\},$$

as required. The case when $T \in \mathcal{A}_n(\mathbb{R})$ is treated similarly. \square

4.4. Duality, Pólya's curve theorem and generalizations. Let us first establish the duality property stated in Theorem 1.11.

of Theorem 1.11. By Theorem 1.2 we have that $T \in \mathcal{A}_n(\mathbb{C})$ if and only if

$$G(z, w) := F_T(z, -w) \in \mathcal{H}_n(\mathbb{C}).$$

But $F_{T^*}(z, -w) = \overline{G(-\bar{w}, -\bar{z})} \in \mathcal{H}_n(\mathbb{C})$ so the desired conclusion follows from Theorem 1.2. The same arguments combined with Theorem 1.3 prove the analogous statement for $\mathcal{A}_n(\mathbb{R})$. \square

In view of Theorem 1.11 one can both recover known results and deduce new ones by a simple dualization procedure, as illustrated in the following examples.

Example 4.2 ((Hermite-Poulain-Jensen theorem)). Let $p(z) = \sum_{k=0}^n a_k z^k \in \mathbb{R}[z] \setminus \{0\}$, $T = p(d/dz) = \sum_{k=0}^n a_k d^k/dz^k \in \mathcal{A}_1[\mathbb{R}]$, and let T_p be the linear operator on $\mathbb{R}[z]$ defined by $T_p(f)(z) = p(z)f(z)$. Then $T^* = T_p$ so by Theorem 1.11 one has $T \in \mathcal{A}_1(\mathbb{R})$ if and only if $T_p \in \mathcal{A}_1(\mathbb{R})$, which clearly holds if and only if $p \in \mathcal{H}_1(\mathbb{R})$.

Example 4.3. The main result of [1] (Theorem 1.4 in *op. cit.*) shows that any operator in $\mathcal{A}_1(\mathbb{R})$ that commutes with the “inverted plane differentiation” operator $D_{\sharp} = z^2 D$, where $D = d/dz$, is of the form αD_{\sharp}^k for some $k \in \mathbb{N}$ and $\alpha \in \mathbb{R}$. Therefore, by Theorem 1.11 we conclude that any operator in $\mathcal{A}_1(\mathbb{R})$ that commutes with the operator $zD^2 = D_{\sharp}^*$ is of the form $\alpha(zD^2)^k$ for some $k \in \mathbb{N}$ and $\alpha \in \mathbb{R}$.

As we will now explain, both Theorem 1.3 and Theorem 1.11 admit natural geometric interpretations that lead to further interesting consequences. For simplicity’s sake, we will only focus on the case $n = 1$.

Definition 4.2. Let $f(z, w) \in \mathbb{R}[z, w]$ be a nonzero polynomial in two variables of (total) degree d and define the real algebraic curve Γ_f (of degree d) by

$$\Gamma_f = \{(z, w) \in \mathbb{R}^2 : f(z, w) = 0\}.$$

We say that f , or equivalently Γ_f , has the *intersection property* (\mathcal{I}_+) if Γ_f has d real intersection points (counted with multiplicities) with any line in \mathbb{R}^2 of the form

$$w = \alpha z + \beta, \quad \text{where } \alpha > 0, \beta \in \mathbb{R}.$$

Similarly, we say that f (or Γ_f) has the *intersection property* (\mathcal{I}_-) if Γ_f has d real intersection points (counted with multiplicities) with any line in \mathbb{R}^2 of the form

$$w = \alpha z + \beta, \quad \text{where } \alpha < 0, \beta \in \mathbb{R}.$$

The *symbol curve* of an operator $T \in \mathcal{A}_1[\mathbb{R}]$ with symbol $F_T(z, w) \in \mathbb{R}[z, w]$ of degree d is the real algebraic curve (of degree d) given by

$$\Gamma_T = \{(z, w) \in \mathbb{R}^2 : F_T(z, w) = 0\}.$$

From Lemma 2.1 and Definition 4.2 we get:

Corollary 4.8. *Let f be a nonzero real polynomial in two variables. Then $f \in \mathcal{H}_2(\mathbb{R})$ if and only if Γ_f has the intersection property (\mathcal{I}_+).*

Therefore, in the univariate case Theorem 1.3 may be restated as follows.

Corollary 4.9. *Let $T \in \mathcal{A}_1[\mathbb{R}]$. Then $T \in \mathcal{A}_1(\mathbb{R})$ if and only if its symbol curve Γ_T has the intersection property (\mathcal{I}_-).*

As depicted in Figure 2 below, Corollary 4.9 essentially allows one to visualize whether an operator $T \in \mathcal{A}_1[\mathbb{R}]$ preserves hyperbolicity by checking whether all lines in \mathbb{R}^2 with negative slope has the required number of intersection points with Γ_T .

In the same spirit, a simple geometric interpretation and proof of Theorem 1.11 for $n = 1$ is as follows: if $T \in \mathcal{A}_1[\mathbb{R}]$ then $F_{T^*}(z, w) = F_T(w, z)$ so Γ_{T^*} is just the reflection of Γ_T in the main diagonal in the zw -plane (i.e., the line $w = z$). Since the intersection property (\mathcal{I}_-) is clearly invariant under this reflection we conclude that Γ_T and Γ_{T^*} have the aforementioned property simultaneously.

These geometric reformulations of Theorem 1.3 and Theorem 1.11 provide a unifying framework for “curve type theorems” that include and considerably strengthen Pólya’s original result [48] and its various known generalizations [18].

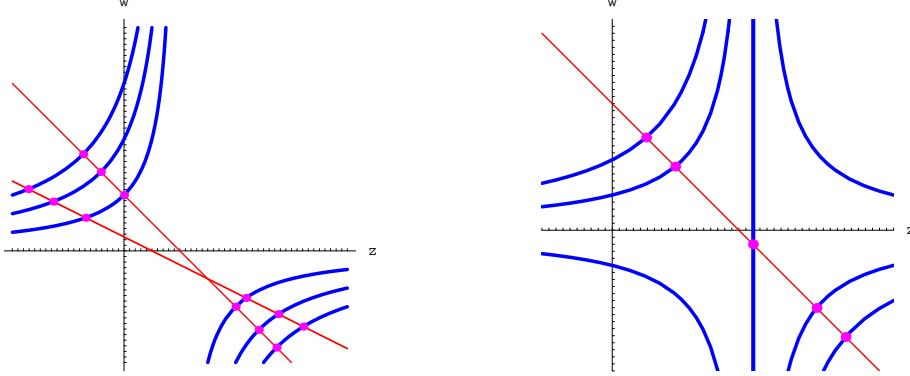


FIGURE 2. Left picture: the symbol curve of degree $d = 6$ of an operator in $\mathcal{A}_1(\mathbb{R})$. Right picture: the symbol curve of degree $d = 7$ of an operator in $\mathcal{A}_1[\mathbb{R}]$ for which property (\mathcal{I}_-) fails.

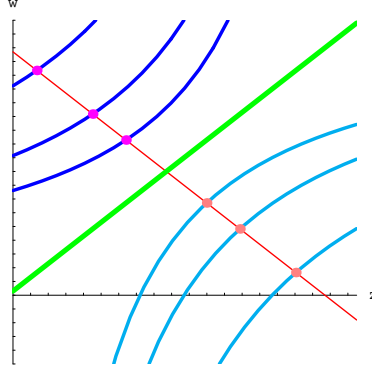


FIGURE 3. The symbol curve Γ_T of degree $d = 3$ of an operator $T \in \mathcal{A}_1(\mathbb{R})$ and its dual curve Γ_{T^*} .

Example 4.4. In [48] Pólya proved the following result that he considered as the most general theorem on the reality of roots of algebraic equations known at the time (1916).

Theorem 4.10 ((Pólya's curve theorem)). *Let $f(x)$ be a (nonzero) hyperbolic polynomial of degree n , and let $b_0 + b_1x + \dots + b_{n+m}x^{n+m}$, where $m \geq 0$, be a hyperbolic polynomial with $b_i > 0$ for all $0 \leq i \leq n$. Set*

$$G_1(x, y) = b_0f(y) + b_1xf'(y) + b_2x^2f''(y) + \dots + b_nf^{(n)}(y) \in \mathbb{R}[x, y].$$

Then G has the intersection property (\mathcal{I}_+) .

Proof. By assumption the polynomial $q(x) = \sum_{k=0}^{n+m} b_kx^k$ has only real and nonpositive zeros hence $q(-xz) \in \mathcal{H}_2(\mathbb{R})$ and thus the polynomial in variables x, y, z given by $q(-xz)f(y)$ belongs to $\mathcal{H}_3(\mathbb{R})$. From Corollary 3.10 we then get $q(xD_y)f(y) \in \mathcal{H}_2(\mathbb{R})$, where $D_y = d/dy$, and the result follows by Corollary 4.8. \square

5. STRICT STABILITY AND STRICT REAL STABILITY PRESERVERS

A natural question in the present context is to characterize all finite order linear differential operators that preserve *strict stability* and *strict real stability*, respectively. These notions are defined as follows: note first that the set of real stable univariate polynomials coincides with the set of hyperbolic univariate polynomials. Denote by $\mathcal{H}_1^s(\mathbb{R})$ the set of all *strictly hyperbolic* univariate polynomials, i.e., polynomials in $\mathcal{H}_1(\mathbb{R})$ with only simple zeros.

Definition 5.1. A polynomial $f \in \mathcal{H}_n(\mathbb{R})$ is called *strictly real stable* if $f(\alpha + vt) \in \mathcal{H}_1^s(\mathbb{R})$ for any $\alpha \in \mathbb{R}^n$ and $v \in \mathbb{R}_+^n$. One calls a polynomial $g \in \mathcal{H}_n(\mathbb{C})$ *strictly stable* if $g(z_1, \dots, z_n) \neq 0$ for all n -tuples $(z_1, \dots, z_n) \in \mathbb{C}^n$ with $\Im(z_j) \geq 0$.

Let $\mathcal{H}_n^s(\mathbb{C})$ (respectively, $\mathcal{H}_n^s(\mathbb{R})$) be the set of all strictly stable (respectively, strictly real stable) polynomials in n variables. Clearly, if $n \geq 2$ then $\mathcal{H}_n^s(\mathbb{R}) = \mathcal{H}_n^s(\mathbb{C}) \cap \mathbb{R}[z_1, \dots, z_n]$ while $\mathcal{H}_1^s(\mathbb{C}) \cap \mathbb{R}[z] = \mathbb{R} \setminus \{0\}$. Denote by $\mathcal{A}_n^s(\mathbb{C})$ and $\mathcal{A}_n^s(\mathbb{R})$ the submonoids of $\mathcal{A}_n[\mathbb{C}]$ and $\mathcal{A}_n[\mathbb{R}]$ consisting of all strict stability and strict real stability preservers, respectively, i.e., $\mathcal{A}_n^s(\mathbb{C}) = \{T \in \mathcal{A}_n[\mathbb{C}] : T(\mathcal{H}_n^s(\mathbb{C})) \subseteq \mathcal{H}_n^s(\mathbb{C}) \cup \{0\}\}$ and $\mathcal{A}_n^s(\mathbb{R}) = \{T \in \mathcal{A}_n[\mathbb{R}] : T(\mathcal{H}_n^s(\mathbb{R})) \subseteq \mathcal{H}_n^s(\mathbb{R}) \cup \{0\}\}$.

In this section we give necessary and sufficient conditions in order for a linear operator to belong to either $\mathcal{A}_n^s(\mathbb{C})$ or $\mathcal{A}_n^s(\mathbb{R})$.

Theorem 5.1. *Let $T \in \mathcal{A}_n[\mathbb{C}]$. If $T \in \mathcal{A}_n^s(\mathbb{C})$ then $F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \neq 0$ whenever $\Im(z_j) \geq 0$ and $\Im(w_k) > 0$ for all $1 \leq j, k \leq n$.*

Theorem 5.2. *Let $T \in \mathcal{A}_n[\mathbb{R}]$. If $T \in \mathcal{A}_n^s(\mathbb{R})$ then $F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \neq 0$ whenever $\Im(z_j) \geq 0$ and $\Im(w_k) > 0$ for all $1 \leq j, k \leq n$.*

To prove Theorems 5.1 and 5.2 we need to establish a multivariate extension of the following classical result [45, 51], compare with Theorems 1.5 and 1.6.

Theorem 5.3 ((Strict Obreschkoff theorem)). *Let $f, g \in \mathbb{R}[z]$. Then*

$$\{\alpha f + \beta g : \alpha, \beta \in \mathbb{R}, \alpha^2 + \beta^2 > 0\} \subset \mathcal{H}_1^s(\mathbb{R})$$

if and only if $f + ig \in \mathcal{H}_1^s(\mathbb{C})$ or $g + if \in \mathcal{H}_1^s(\mathbb{C})$.

Theorem 5.4. *Let $f, g \in \mathbb{R}[z_1, \dots, z_n]$. Then*

$$\{\alpha f + \beta g : \alpha, \beta \in \mathbb{R}, \alpha^2 + \beta^2 > 0\} \subset \mathcal{H}_n^s(\mathbb{R})$$

if and only if $f + ig \in \mathcal{H}_n^s(\mathbb{C})$ or $g + if \in \mathcal{H}_n^s(\mathbb{C})$.

Proof. This is an immediate consequence of Definition 5.1 and Theorem 5.3. \square

of Theorem 5.1. Suppose that $T \in \mathcal{A}_n^s(\mathbb{C})$ and let $f \in \mathcal{H}_n(\mathbb{C})$. Then

$$f_\epsilon(z_1, \dots, z_n) := f(z_1 + i\epsilon, \dots, z_n + i\epsilon) \in \mathcal{H}_n^s(\mathbb{C})$$

for all $\epsilon > 0$, so $T(f_\epsilon) \in \mathcal{H}_n^s(\mathbb{C})$. Letting $\epsilon \rightarrow 0$ it follows from Hurwitz' theorem that $T(f) \in \mathcal{H}_n(\mathbb{C}) \cup \{0\}$ and thus $T \in \mathcal{A}_n(\mathbb{C})$. Now Theorem 1.2 implies that

$$F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) := \sum_{\alpha \in \mathbb{N}^n} Q_\alpha(z_1, \dots, z_n)(-w)^\alpha \in \mathcal{H}_{2n}(\mathbb{C}),$$

where $Q_\alpha \in \mathbb{C}[z_1, \dots, z_n]$ are not identically zero only for a finite number of multi-indices $\alpha \in \mathbb{N}^n$. Fix $(z_1^0, \dots, z_n^0) \in \mathbb{C}^n$ with $\Im(z_i^0) \geq 0$, $1 \leq i \leq n$. Then for any $\epsilon > 0$ one has $\Im(z_k^0 + i\epsilon) > 0$ for all $1 \leq k \leq n$. Hence

$$\sum_{\alpha \in \mathbb{N}^n} Q_\alpha(z_1^0 + i\epsilon, \dots, z_n^0 + i\epsilon)(-w)^\alpha \in \mathcal{H}_n(\mathbb{C})$$

and by letting $\epsilon \rightarrow 0$ we deduce that

$$\sum_{\alpha \in \mathbb{N}^n} Q_\alpha(z_1^0, \dots, z_n^0)(-w)^\alpha \in \mathcal{H}_n(\mathbb{C}) \cup \{0\}.$$

If $\sum_{\alpha \in \mathbb{N}^n} Q_\alpha(z_1^0, \dots, z_n^0)(-w)^\alpha \equiv 0$ then $Q_\alpha(z_1^0, \dots, z_n^0) = 0$ for all $\alpha \in \mathbb{N}^n$ and consequently $T(f)(z_1^0, \dots, z_n^0) = 0$ for all polynomials f , which contradicts the assumption that $T \in \mathcal{A}_n^s(\mathbb{C})$ and $\Im(z_i^0) \geq 0$ for all $1 \leq i \leq n$. \square

of Theorem 5.2. Suppose that $T \in \mathcal{A}_n^s(\mathbb{R})$. If the symbol is not as in the statement of the theorem then by arguing as in the proof of the necessity in Theorem 5.1 we see that there exists $Z^0 = (z_1^0, \dots, z_n^0) \in \mathbb{C}^n$ with $\Im(z_i^0) \geq 0$, $1 \leq i \leq n$, and

$$F(Z^0, -w) = 0 \quad (7)$$

as a polynomial in $w = (w_1, \dots, w_n)$. Choose a polynomial $f \in \mathcal{H}_n^s(\mathbb{R})$ of sufficiently high degree so that $T(\alpha f + \beta \partial_1 f) \neq 0$ whenever $\alpha^2 + \beta^2 > 0$. By Theorem 5.4 we have $T(f) + iT(\partial_1 f) \in \mathcal{H}_n^s(\mathbb{C})$. This is however a contradiction since by (7) we have $T(f)(Z^0) + iT(\partial_1 f)(Z^0) = 0$. \square

The next two theorems give sufficient conditions for operators in the Weyl algebra to be strict stability or strict real stability preserving, respectively.

Theorem 5.5. *Let $T \in \mathcal{A}_n[\mathbb{C}]$. If $F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \in \mathcal{H}_{2n}^s(\mathbb{C})$ then $T \in \mathcal{A}_n^s(\mathbb{C})$.*

Theorem 5.6. *Let $T \in \mathcal{A}_n[\mathbb{R}]$. If $F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \in \mathcal{H}_{2n}^s(\mathbb{R})$ then $T \in \mathcal{A}_n^s(\mathbb{R})$.*

of Theorem 5.5. Let $T \in \mathcal{A}_n[\mathbb{C}]$ and suppose that

$$F_T(z_1, \dots, z_n, -w_1, \dots, -w_n) \neq 0$$

whenever $\Im(z_i) \geq 0$ and $\Im(w_j) \geq 0$ for all $1 \leq i, j \leq n$. If $f(v_1, \dots, v_n) \in \mathcal{H}_n^s(\mathbb{C})$ then

$$F_T(z_1, \dots, z_n, -w_1, \dots, -w_n)f(v_1, \dots, v_n) \neq 0$$

provided that $\Im(z_i) \geq 0$, $\Im(w_j) \geq 0$ and $\Im(v_k) \geq 0$ for all $1 \leq i, j, k \leq n$. By Proposition 3.9 we may replace each variable w_j with $w_j - \partial/\partial v_j$ for all $1 \leq j \leq n$, to get

$$F_T\left(z_1, \dots, z_n, \frac{\partial}{\partial v_1} - w_1, \dots, \frac{\partial}{\partial v_n} - w_n\right)f(v_1, \dots, v_n) \neq 0$$

whenever $\Im(z_i) \geq 0$, $\Im(v_i) \geq 0$, $\Im(w_i) \geq 0$ for $1 \leq i \leq n$. If we now exchange each variable v_j by z_j for all $1 \leq j \leq n$, and let $w_i = 0$ for all $1 \leq i \leq n$, we see that

$$T(f)(z_1, \dots, z_n) = F_T\left(z_1, \dots, z_n, \frac{\partial}{\partial z_1}, \dots, \frac{\partial}{\partial z_n}\right)f(z_1, \dots, z_n) \neq 0$$

whenever $\Im(z_i) \geq 0$, $1 \leq i \leq n$, hence $T(f) \in \mathcal{H}_n^s(\mathbb{C})$. \square

of Theorem 5.6. If F_T is as in the statement of the theorem then by Theorem 5.5 we have that $T \in \mathcal{A}_n^s(\mathbb{C})$. Consider $f \in \mathcal{H}_n^s(\mathbb{R})$. The case when f is a nonzero constant, say $f(z) \equiv c \in \mathbb{R} \setminus \{0\}$, is immediate since $T(f)(z_1, \dots, z_n) = cF_T(z_1, \dots, z_n, 0, \dots, 0) \neq 0$ whenever $\Im(z_i) \geq 0$, $1 \leq i \leq n$, hence $T(f) \in \mathcal{H}_n^s(\mathbb{R})$. Suppose that f is not a constant polynomial. By re-indexing the variables we may assume that $\partial_1 f \neq 0$. Then $f + i\partial_1 f \in \mathcal{H}_n^s(\mathbb{C})$, so $T(f) + iT(\partial_1 f) \in \mathcal{H}_n^s(\mathbb{C}) \cup \{0\}$. By Theorem 5.4 we have that $T(f) \in \mathcal{H}_n^s(\mathbb{R}) \cup \{0\}$, as required. \square

To close this section we note that in general the necessary conditions stated in Theorems 5.1 and 5.2 are not sufficient while the sufficient conditions given in Theorems 5.5–5.6 are not necessary. This may be seen already in the univariate case from the following simple examples. The operator $T = d/dz$ is clearly strict (real) stability preserving but its symbol $F_T(z, w) = w$ does not satisfy the sufficient conditions stated in Theorems 5.5 and 5.6. Consider now the operator $S = 2z + 1 + (z^2 + z)d/dz$. One can easily check that $F_S(z, -w) \neq 0$ whenever $\Im(z) \geq 0$ and $\Im(w) > 0$ and also that S preserves strictly real stable (i.e., strictly hyperbolic) polynomials. However, $S(1) = 2z + 1 \notin \mathcal{H}_1^s(\mathbb{C})$ so $S \notin \mathcal{A}_1^s(\mathbb{C})$. A characterization of strict (real) stability preservers would therefore require conditions that are intermediate between those of Theorems 5.1 and 5.2 and Theorems 5.5 and 5.6.

6. MULTIVARIATE MATRIX PENCILS AND APPLICATIONS

We will now give several examples and applications of the above results. First we prove Proposition 1.12 claiming that the polynomial

$$f(z_1, \dots, z_n) := \det \left(\sum_{i=1}^n z_i A_i + B \right)$$

with A_1, \dots, A_n positive semidefinite matrices and B a Hermitian matrix of the same order is either real stable or identically zero.

of Proposition 1.12. By a standard continuity argument using Hurwitz' theorem it suffices to prove the result only in the case when all matrices A_1, A_2, \dots, A_n are positive definite. Set $z(t) = \alpha + \lambda t$ with $\alpha \in \mathbb{R}^n$, $\lambda \in \mathbb{R}_+^n$ and $t \in \mathbb{R}$. Note that $P := \lambda_1 A_1 + \dots + \lambda_n A_n$ is positive definite and thus it has a square root. Then $f(z(t)) = \det(P) \det(tI + P^{-1/2} H P^{-1/2})$, where $H := B + \alpha_1 A_1 + \dots + \alpha_n A_n$. Since $f(z(t))$ is a constant multiple of the characteristic polynomial of the Hermitian matrix H , it has only real zeros. \square

6.1. A stable multivariate extension of the Cauchy-Poincaré theorem. Let A be any $n \times n$ complex matrix and define a polynomial $C(A, z) = \det(Z - A) \in \mathbb{C}[z_1, \dots, z_n]$, where $z = (z_1, \dots, z_n)$ and Z is the (diagonal) matrix with entries $Z_{ij} = z_i \delta_{ij}$. Given $1 \leq i, j \leq n$ let A^{ij} be the submatrix of A obtained by deleting row i and column j and set $C_{ij}(A, z) = \det((Z - A)^{ij})$. For $z = (z_1, \dots, z_n)$ and $1 \leq i \leq n$ let $z \setminus z_i = (z_1, \dots, z_{i-1}, z_{i+1}, \dots, z_n)$, so that $C_{ii}(A, z) = C(A^{ii}, z \setminus z_i)$.

Lemma 6.1. *For $1 \leq j \leq n$ one has $T_j := 1 + i\partial/\partial z_j \in \mathcal{A}_n(\mathbb{C})$.*

Proof. The symbol $F_{T_j}(z, w)$ of T_j is $F_{T_j}(z, -w) = 1 - iw_j$ and the latter polynomial is stable since it is obviously nonvanishing if $\Im(w_j) > 0$. The assertion now follows from Theorem 1.2. \square

Theorem 6.2. *If A is a complex Hermitian $n \times n$ matrix then $C(A, z) \in \mathcal{H}_n(\mathbb{R})$ and*

$$C(A^{jj}, z \setminus z_j) \ll C(A, z)$$

for $1 \leq j \leq n$.

Proof. Note that since A is Hermitian $C(A, z)$ is real stable by Proposition 1.12. Now

$$C(A^{jj}, z \setminus z_j) = C_{jj}(A, z) = \frac{\partial}{\partial z_j} C(A, z) \ll C(A, z)$$

by Lemma 6.1 and Corollary 2.4. \square

The above theorem generalizes the classical Cauchy-Poincaré theorem stating that the eigenvalues of a Hermitian matrix and those of any of its degeneracy one principal submatrices interlace.

An alternative proof of Theorem 6.2 may be obtained by using the following consequence of the Christoffel-Darboux identity [27]:

Lemma 6.3. *Let A be any $n \times n$ matrix with $n \geq 2$ and let $1 \leq i, j \leq n$. Then*

$$C(A, y)C_{ij}(A, x) - C(A, x)C_{ij}(A, y) = \sum_{k=1}^n (y_k - x_k)C_{ik}(A, x)C_{kj}(A, y). \quad (8)$$

Proof. Let $X = (x_i \delta_{ij})$ and $Y = (y_i \delta_{ij})$. The identity

$$(X - A)^{-1} - (Y - A)^{-1} = (X - A)^{-1}(Y - X)(Y - A)^{-1}$$

obtains by multiplying on the left with $(X - A)$ and on the right with $(Y - A)$. Taking the ij -th entry on both sides in the above identity and multiplying by $C(A, x)C(A, y)$ yields formula (8). \square

Now let A be a complex Hermitian $n \times n$ matrix with $n \geq 2$ and let $y = z$, $x = \bar{z}$ and $i = j$ in (8). Note that $C_{ij}(A, \bar{z}) = \overline{C_{ji}(A, z)}$ and since $C_{ii}(A, z) = C(A^{ii}, z \setminus z_i)$ we get

$$\Im(C(A, z)C(A^{ii}, \overline{z \setminus z_i})) = \sum_{k=0}^n \Im(z_k) |C_{ik}(A, z)|^2. \quad (9)$$

Theorem 6.2 is obviously true for $n = 1$ and the general case follows by induction on n . Indeed, let $\Im(z_j) > 0$ for $1 \leq j \leq n$, where $n \geq 2$. By the induction hypothesis we have $C(A^{ii}, z \setminus z_i) \in \mathcal{H}_{n-1}(\mathbb{C})$ and then from (9) we deduce that

$$\Im \left(\frac{C(A, z)}{C(A^{ii}, z \setminus z_i)} \right) = \Im \left(\frac{C(A, z)C(A^{ii}, \overline{z \setminus z_i})}{|C(A^{ii}, z \setminus z_i)|^2} \right) \geq \Im(z_i) > 0.$$

Hence $C(A, z) \neq 0$ and the desired conclusion follows from Lemma 2.2.

6.2. Lax conjecture for real stable polynomials in two variables. Here we will prove that all real stable polynomials in two variables x, y can be written as $\pm \det(xA + yB + C)$, where A and B are positive semidefinite (PSD) matrices and C is a symmetric matrix. The proof relies on the Lax conjecture that was recently settled in [38] by using in an essential way the results of [30].

Theorem 6.4 ([30, 38]). *A homogeneous polynomial $p \in \mathbb{R}[x, y, z]$ is hyperbolic of degree d with respect to the vector $e = (1, 0, 0)$ if and only if there exist two symmetric $d \times d$ matrices B, C such that*

$$p(x, y, z) = p(e) \det(xI + yB + zC).$$

We will also need Proposition 1.1 that we proceed to prove.

of Proposition 1.1. If $f \in \mathbb{R}[z_1, \dots, z_n]$ is of degree d then its *homogenization* – i.e., the unique homogeneous polynomial $f_H \in \mathbb{R}[z_1, \dots, z_{n+1}]$ of degree d such that $f_H(z_1, \dots, z_n, 1) = f(z_1, \dots, z_n)$ – is simply

$$f_H(z_1, \dots, z_{n+1}) = z_{n+1}^d f(z_1 z_{n+1}^{-1}, \dots, z_n z_{n+1}^{-1}).$$

If f_H is hyperbolic with respect to every vector $v \in \mathbb{R}^{n+1}$ such that $v_{n+1} = 0$ and $v_i > 0$, for all $1 \leq i \leq n$, it follows in particular that for any $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{R}^n$ and $(v_1, \dots, v_n) \in \mathbb{R}_+^n$ the univariate (real) polynomial in t given by

$$f_H((\alpha_1, \dots, \alpha_n, 1) + (v_1, \dots, v_n, 0)t) = f(\alpha + vt)$$

is not identically zero (since $\lim_{t \rightarrow \infty} t^{-d} f(\alpha + vt) = f_H(v_1, \dots, v_n, 0) \neq 0$) and has only real zeros. Hence it belongs to $\mathcal{H}_1(\mathbb{R})$. Thus $f \in \mathcal{H}_n(\mathbb{R})$ by Lemma 2.1.

Conversely, suppose that $f \in \mathcal{H}_n(\mathbb{R})$ has degree d and is given by

$$f(z) = \sum_{\kappa \in \mathbb{N}^n} a_\kappa z^\kappa, \quad z = (z_1, \dots, z_n).$$

Let $\alpha = (\alpha_1, \dots, \alpha_{n+1}) \in \mathbb{R}^{n+1}$ and $v = (v_1, \dots, v_{n+1}) \in \mathbb{R}^{n+1}$ with $v_{n+1} = 0$ and $v_i > 0$ for all $1 \leq i \leq n$. Since $a_\kappa \neq 0$ for some $\kappa \in \mathbb{N}^n$ with $|\kappa| = d$, Hurwitz' theorem yields

$$g(z) := \lim_{t \rightarrow \infty} t^{-d} f(tz) = \sum_{\kappa \in \mathbb{N}^n, |\kappa|=d} a_\kappa z^d \in \mathcal{H}_n(\mathbb{R}).$$

Moreover, g is a homogeneous polynomial so by the “same phase property” established in [16, Theorem 6.1] all nonzero a_κ 's with $|\kappa| = d$ have the same sign. Therefore

$$f_H(v) = g(v_1, \dots, v_n) = \sum_{\kappa \in \mathbb{N}^n, |\kappa|=d} a_\kappa v_1^{\kappa_1} \cdots v_n^{\kappa_n} \neq 0$$

since $v_i > 0$ for all $1 \leq i \leq n$. Now, if $\alpha_{n+1} = 0$ then the univariate polynomial

$$t \mapsto f_H(\alpha + vt) = g(\alpha_1 + v_1 t, \dots, \alpha_n + v_n t)$$

has only real zeros by Lemma 2.1, while if $\alpha_{n+1} > 0$ then again by Lemma 2.1 the univariate polynomial

$$t \mapsto f_H(\alpha + vt) = \alpha_{n+1}^d f(\alpha_1 \alpha_{n+1}^{-1} + v_1 \alpha_{n+1}^{-1} t, \dots, \alpha_n \alpha_{n+1}^{-1} + v_n \alpha_{n+1}^{-1} t)$$

has only real zeros. By the last part of Lemma 2.1, the same holds when $\alpha_{n+1} < 0$. Hence f_H is hyperbolic with respect to all vectors $v \in \mathbb{R}^{n+1}$ as above. \square

Lemma 6.5. *Suppose that $p \in \mathbb{R}[x, y, z]$ is a homogeneous polynomial of degree d which is hyperbolic with respect to any $(v_1, v_2, 0) \in \mathbb{R}^3$ with $v_1, v_2 \in \mathbb{R}_+$. Then*

$$p(x, y, 0) = \sum_{i=0}^d a_i x^{d-i} y^i,$$

where the a_i 's are such that $\sum_{i=0}^d a_i t^i$ is a polynomial with only nonpositive zeros.

Proof. By letting $z \rightarrow 0$ it follows from Hurwitz' theorem that $p(x, y, 0)$ is hyperbolic with respect to all $v \in \mathbb{R}_+^2$, so it is stable by Proposition 1.1. By [16, Theorem 6.1] all the coefficients have the same sign. Since $p(x, y, 0)$ is stable all the zeros of the polynomial where $p(1, t, 0) = a_0 + a_1 t + \cdots + a_d t^d$ are real and since the coefficients have the same sign all the zeros are nonpositive. \square

Theorem 6.6. *A homogeneous polynomial $p \in \mathbb{R}[x, y, z]$ of degree d is hyperbolic with respect to all vectors of the form $(v_1, v_2, 0)$ with $v_1, v_2 \in \mathbb{R}_+$ if and only if there exist two positive semidefinite $d \times d$ matrices A and B and a symmetric $d \times d$ matrix C such that*

$$p(x, y, z) = \alpha \det(xA + yB + zC),$$

where $\alpha \in \mathbb{R}$. Moreover, A and B can be chosen so that $A + B = I$.

Proof. Let p be hyperbolic of degree d with respect to all vectors of the form $(v_1, v_2, 0)$ with $v_1, v_2 \in \mathbb{R}_+$ and let $\alpha := p(1, 1, 0) \in \mathbb{R} \setminus \{0\}$. Consider the polynomial $f(x, y, z) = p(x, x + y, z)$. Then $f(x, y, z)$ is hyperbolic of degree d with respect to all vectors $(v_1, v_2, 0)$, where $v_1, v_2 \in \mathbb{R}_+$. Moreover, it is hyperbolic with respect to the vector $e = (1, 0, 0)$. Hence by Theorem 6.4 there exist two symmetric $d \times d$ matrices B, C such that

$$f(x, y, z) = f(e) \det(xI + yB + zC).$$

Since f is hyperbolic with respect to all vectors of the form $(v_1, v_2, 0)$ with $v_1, v_2 \in \mathbb{R}_+$ we know by Lemma 6.5 that all the eigenvalues of B are nonnegative. Hence B is a PSD matrix. Let $A = I - B$. Then

$$p(x, y, z) = \alpha \det(xA + y(I - A) + zC),$$

and by Lemma 6.5 all zeros of the polynomial

$$r(t) := \alpha^{-1} p(1, t, 0) = (1 - t)^d \det\left(A + \frac{t}{1 - t}I\right) \in \mathbb{R}[t]$$

are nonpositive. Inverting this we have

$$\det(A + tI) = (1 + t)^d r\left(\frac{t}{1 + t}\right),$$

which implies that A has only nonnegative eigenvalues, so that A is a PSD matrix. \square

From Theorem 6.6 and Proposition 1.1 we deduce the following converse to Proposition 1.12 for real stable polynomials in two variables.

Corollary 6.7. *Let $f(x, y) \in \mathbb{R}[x, y]$ be of degree n . Then f is real stable if and only if there exist two $n \times n$ PSD matrices A, B and a symmetric $n \times n$ matrix C such that*

$$f(x, y) = \pm \det(xA + yB + C).$$

6.3. Hyperbolicity preservers via determinants and homogenized symbols. Using Theorem 1.3 with $n = 1$ and Corollary 6.7 we immediately get the following determinantal description of finite order linear preservers of univariate real stable (i.e., hyperbolic) polynomials.

Theorem 6.8. *Let $T \in \mathcal{A}_1[\mathbb{R}]$. Then $T \in \mathcal{A}_1(\mathbb{R})$ if and only if there exist $\alpha \in \mathbb{R}$, $d \in \mathbb{N}$, two positive semidefinite $d \times d$ matrices A and B and a symmetric $d \times d$ matrix C such that*

$$T = \alpha \det(zA - wB + C) \Big|_{w=\partial/\partial z}.$$

From Theorem 6.8 and Proposition 1.1 we deduce yet another characterization of univariate hyperbolicity preservers involving real homogeneous (Gårding) hyperbolic polynomials in 3 variables:

Theorem 6.9. *Let $T \in \mathcal{A}_1[\mathbb{R}]$ with symbol $F_T(z, w)$ of degree d and let $\tilde{F}_T(y, z, w)$ be the (unique) homogeneous degree d polynomial such that $\tilde{F}_T(1, z, w) = F_T(z, w)$. Then $T \in \mathcal{A}_1(\mathbb{R})$ if and only if the following conditions hold:*

- (i) $\tilde{F}_T(y, z, w)$ is hyperbolic with respect to $(0, 1, 1)$,
- (ii) all zeros of $\tilde{F}_T(0, t, 1)$ lie in $(-\infty, 0]$.

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